

LDC1001-Q1 电感数字转换器

1 特性

- 符合面向汽车应用的 AEC-Q100 标准：
 - 温度等级 0: -40°C 至 150°C, T_A
- 无磁体操作
- 亚微米高精度
- 可调节感应范围（通过线圈设计实现）
- 更低的系统成本
- 远程传感器放置（从恶劣环境中将 LDC 去耦合）
- 高耐用性（通过非接触式操作实现）
- 不易受到环境干扰因素的影响（诸如污垢、灰尘、水、油）
- 电源电压，模拟：4.75V 至 5.25V
- 电源电压，IO：1.8V 至 5.25V
- 电源电流（不含 LC 振荡电路）：1.7mA
- R_p 分辨率：16 位
- L 分辨率：24 位
- LC 频率范围：5kHz 至 5MHz

2 应用

- 触摸按钮
- 角度位置感应
- 线性位置感应
- 金属接近感应

3 说明

LDC1001-Q1 器件是一款符合汽车标准的 4.75V 至 5.25V 电感数字转换器，专为测量并联电阻 (R_p) 和电感 (L) 而设计。电感式感应技术可以在汽车和工业应用中精确地测量金属目标的线性或角度位置。

电感式感应是一种非接触式短程感应技术，即使在存在污垢、灰尘、油和湿气的恶劣环境中，也能够对导电目标进行高分辨率感应。

LDC1001-Q1 系统由一个电感式传感器（通常是一个 PCB 线圈）和一个导电目标组成。

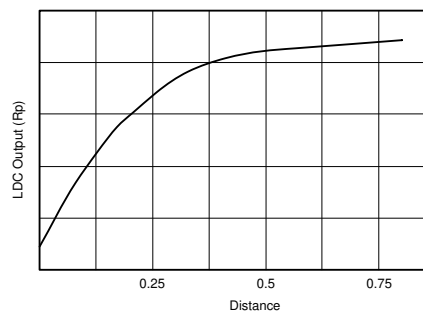
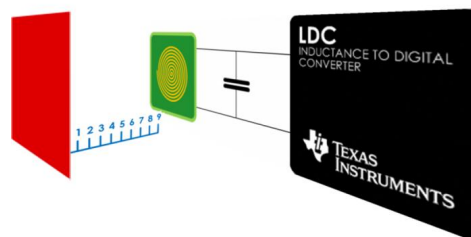
LDC1001-Q1 采用 16 引脚 TSSOP 封装，具有多种运行模式。其串行外设接口 (SPI) 简化了与微控制器 (MCU) 的连接方式。

器件信息⁽¹⁾

器件型号	封装	封装尺寸 (标称值)
LDC1001-Q1	TSSOP (16)	5.00mm × 4.40mm

(1) 要了解所有可用封装，请见数据表末尾的可订购产品附录。

典型应用 — 轴向距离感测



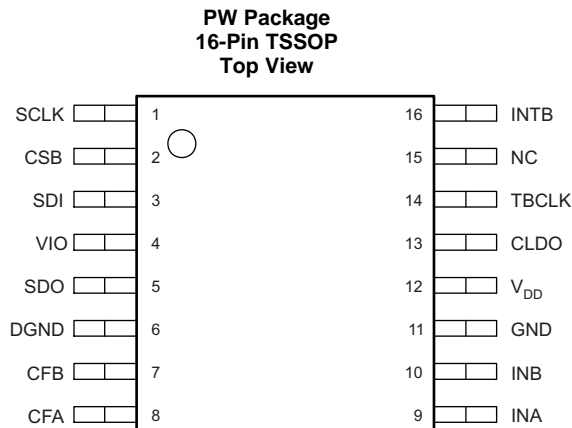
目录

1	特性	1	7.4	Device Functional Modes	12
2	应用	1	7.5	Programming	14
3	说明	1	7.6	Register Map	16
4	修订历史记录	2	8	Application and Implementation	26
5	Pin Configuration and Functions	3	8.1	Application Information	26
6	Specifications	4	8.2	Typical Application	28
6.1	Absolute Maximum Ratings	4	9	Power Supply Recommendations	32
6.2	ESD Ratings	4	10	Layout	32
6.3	Recommended Operating Conditions	4	10.1	Layout Guidelines	32
6.4	Thermal Information	4	10.2	Layout Example	33
6.5	Electrical Characteristics	5	11	器件和文档支持	34
6.6	Timing Requirements	6	11.1	接收文档更新通知	34
6.7	Typical Characteristics	7	11.2	支持资源	34
7	Detailed Description	8	11.3	商标	34
7.1	Overview	8	11.4	静电放电警告	34
7.2	Functional Block Diagram	8	11.5	Glossary	34
7.3	Feature Description	8	12	机械、封装和可订购信息	34

4 修订历史记录

日期	版本	注释
2019 年 11 月	*	初始发行版。

5 Pin Configuration and Functions



Pin Functions

PIN		TYPE ⁽¹⁾	DESCRIPTION
NO.	NAME		
1	SCLK	DI	SPI clock input. The SCLK pin is used to clock-out and clock-in the data from or into the chip
2	CSB	DI	SPI CSB. Multiple devices can be connected on the same SPI bus and the CSB pin can be used to select which device is communicated with.
3	SDI	DI	SPI Slave Data In (Master Out Slave In). This pin should be connected to the Master Out Slave In of the master device.
4	VIO	P	Digital IO Supply
5	SDO	DO	SPI Slave Data Out (Master In Slave Out). This pin is high-Z when the CSB pin is high.
6	DGND	P	Digital ground
7	CFB	A	LDC filter capacitor
8	CFA	A	LDC filter capacitor
9	INA	A	External LC Tank. Connect this pin to an external LC tank.
10	INB	A	External LC Tank. Connect this pin to an external LC tank.
11	GND	P	Analog ground
12	V _{DD}	P	Analog supply
13	CLDO	A	LDO bypass capacitor. Connect a 56-nF capacitor from this pin to GND.
14	TBCLK	DI	External time-base clock
15	NC	NC	This pin should be floating.
16	INTB	DO	Configurable interrupt. This pin can be configured to function in three different ways (threshold detect, wake-up, or DRDYB) by programming the INT pin mode register.

(1) DO: Digital Output, DI: Digital Input, P: Power, A: Analog

6 Specifications

6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)⁽¹⁾

		MIN	MAX	UNIT
Analog supply voltage	V _{DD} – GND		5.5	V
IO supply voltage	V _{IO} – GND		5.5	V
Voltage	On any pin	–0.3	V _{DD} + 0.3	V
	On any digital pin	–0.3	V _{IO} + 0.3	V
Input Current	INA and INB		8	mA
Junction Temperature, T _J			150	°C
Storage temperature, T _{stg}		–65	150	°C

(1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

6.2 ESD Ratings

			VALUE	UNIT
V _(ESD)	Electrostatic discharge	Human body model (HBM), per AEC Q100-002 ⁽¹⁾ HBM Classification Level 2	±2000	V
		Charged device model (CDM), per AEC Q100-011 CDM Classification Level C6	±1000	

(1) AEC Q100-002 indicates HBM stressing is done in accordance with the ANSI/ESDA/JEDEC JS-001 specification.

6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	MAX	UNIT
V _{DD}	Analog supply voltage (V _{DD} – GND)	4.75	5.25	V
V _{IO}	IO supply voltage (V _{IO} – GND)	1.8	5.25	V
	V _{DD} – V _{IO}	≥0		V
T _A	Operating temperature	–40	150	°C

6.4 Thermal Information

THERMAL METRIC ⁽¹⁾		LDC1001-Q1	UNIT
		PW (TSSOP)	
		16 PINS	
R _{θJA}	Junction-to-ambient thermal resistance	106.3	°C/W
R _{θJC(top)}	Junction-to-case (top) thermal resistance	40.8	°C/W
R _{θJB}	Junction-to-board thermal resistance	51.3	°C/W
ψ _{JT}	Junction-to-top characterization parameter	3.6	°C/W
ψ _{JB}	Junction-to-board characterization parameter	50.8	°C/W
R _{θJC(bot)}	Junction-to-case (bottom) thermal resistance	—	°C/W

(1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report (SPRA953).

6.5 Electrical Characteristics

Unless otherwise specified, all limits ensured for $T_A = 25^\circ\text{C}$, $V_{DD} = 5\text{ V}$, $V_{IO} = 3.3\text{ V}$

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
POWER						
V_{DD}	Analog supply voltage		4.75	5	5.25	V
V_{IO}	IO supply voltage	$V_{IO} \leq V_{DD}$	1.8	3.3	5.25	V
I_{DD}	Supply current	Does not include the LC tank current		1.7	2.3	mA
I_{IO}	IO supply current	Static current			14	μA
$I_{DD(LP)}$	Low-power mode supply current	Without LC tank		250		μA
t_{start}	Start-up time	From POR to ready-to-convert.		2		ms
LDC						
$f_{\text{sensor_min}}$	Minimum sensor frequency			5		kHz
$f_{\text{sensor_max}}$	Maximum sensor frequency			5		MHz
$A_{\text{sensor_min}}$	Minimum sensor amplitude			1		V_{PP}
$A_{\text{sensor_max}}$	Maximum sensor amplitude			4		V_{PP}
t_{rec}	Recovery time	Oscillation start-up time after RP under-range condition		10		$1 / f_{\text{sensor}}$
Z_{RP_min}	Minimum sensor RP range			798		Ω
R_{RP_max}	Maximum sensor RP range			3.93		$M\Omega$
R_{RP_res}	RP measurement resolution			16		Bits
$t_{\text{res(min)}}$	Minimum response time	Minimum programmable settling time of digital filter		$192 \times 1 / f_{\text{sensor}}$		s
$t_{\text{res(max)}}$	Maximum response time	Maximum programmable settling time of digital filter		$6144 \times 1 / f_{\text{sensor}}$		s
EXTERNAL CLOCK FOR FREQUENCY COUNTER						
	External clock frequency				8	MHz
	External clock input high voltage				V_{IO}	V
DIGITAL I/O CHARACTERISTICS						
V_{IH}	Logic 1 input voltage		$0.8 \times V_{IO}$			V
V_{IL}	Logic 0 input voltage			$0.2 \times V_{IO}$		V
V_{OH}	Logic 1 output voltage	$I_{\text{SOURCE}} = 400\ \mu\text{A}$		$V_{IO} - 0.3$		V
V_{OL}	Logic 0 output voltage	$I_{\text{SINK}} = 400\ \mu\text{A}$			0.3	V
I_{kgIO}	Digital IO leakage current		-500		500	nA

6.6 Timing Requirements

Unless otherwise noted, all limits specified at $T_A = 25^\circ\text{C}$, $V_{DD} = 5\text{ V}$, $V_{IO} = 3.3\text{ V}$, 10-pF capacitive load in parallel with a 10-k Ω load on the SDO. Specified by design; not production tested. See [Figure 1](#)

			MIN	NOM	MAX	UNIT
f_{SCLK}	Serial clock frequency	See Figure 1			4	MHz
t_{wH}	SCLK pulse-width high	$f_{\text{SCLK}} = 4\text{ Mhz}$, See Figure 1	0.4 / f_{SCLK}			s
t_{wL}	SCLK pulse-width low	$f_{\text{SCLK}} = 4\text{ Mhz}$, See Figure 1	0.4 / f_{SCLK}			s
t_{su}	SDI setup time	See Figure 1	10			ns
t_{h}	SDI hold time		10			ns
t_{ODZ}	SDO driven-to-tristate time	Measured at 10% / 90% point, See Figure 2			20	ns
t_{OZD}	SDO tristate-to-driven time	Measured at 10% / 90% point, See Figure 2			20	ns
$t_{\text{d(OUTPUT)}}$	SDO output delay time	See Figure 2			20	ns
$t_{\text{su(CS)}}$	CSB setup time		20			ns
$t_{\text{h(CS)}}$	CSB hold time		20			ns
t_{IAG}	inter-access gap	See Figure 16	100			ns
$t_{\text{w(DRDY)}}$	Data ready pulse width	Data ready pulse at every 1 / ODR if no data is read	1 / f_{sensor}			s

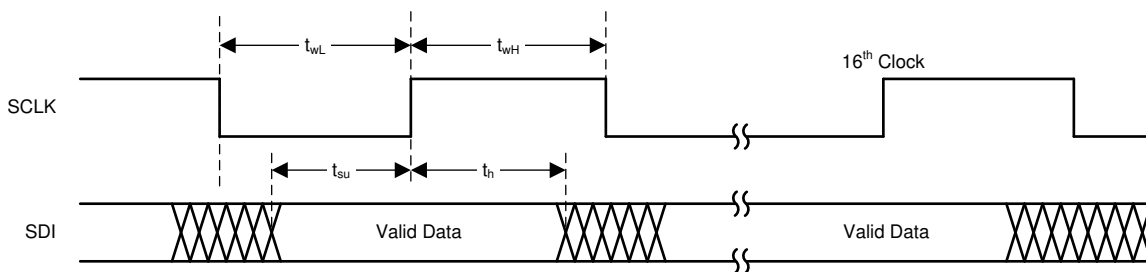


Figure 1. Write Timing Diagram

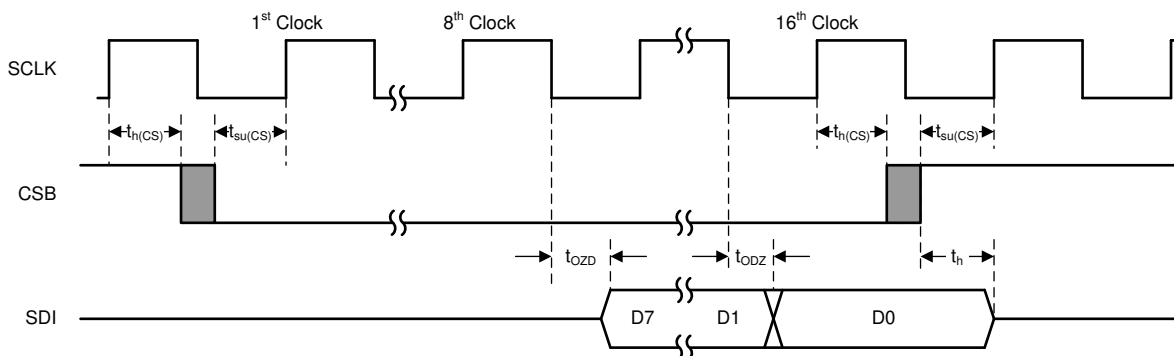
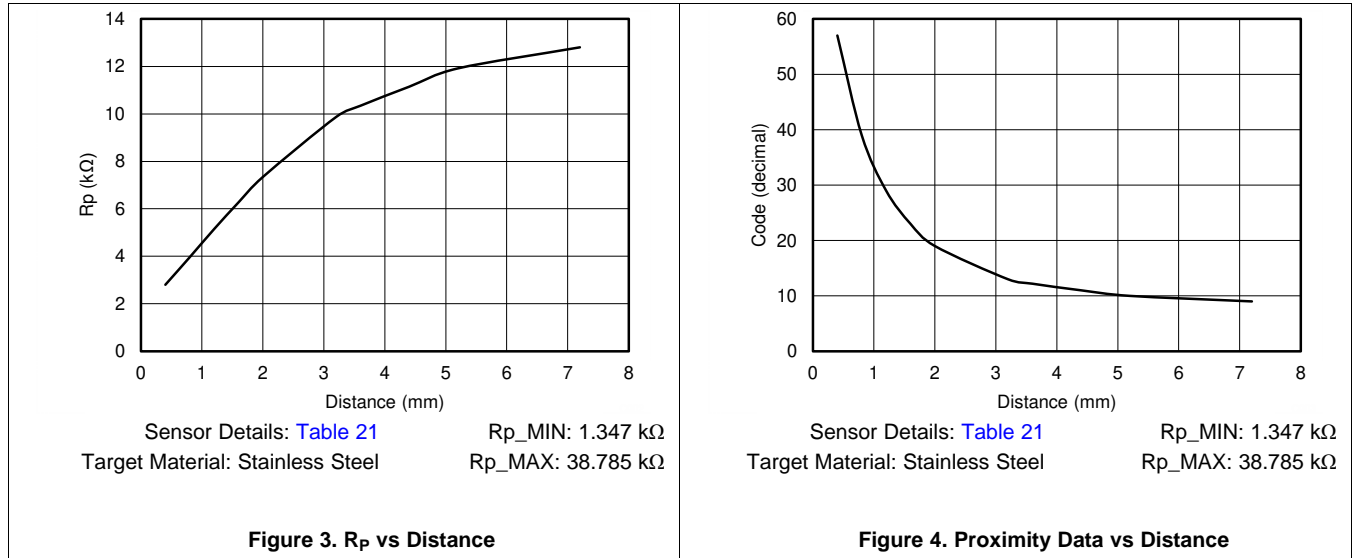


Figure 2. Read Timing Diagram

6.7 Typical Characteristics



7 Detailed Description

7.1 Overview

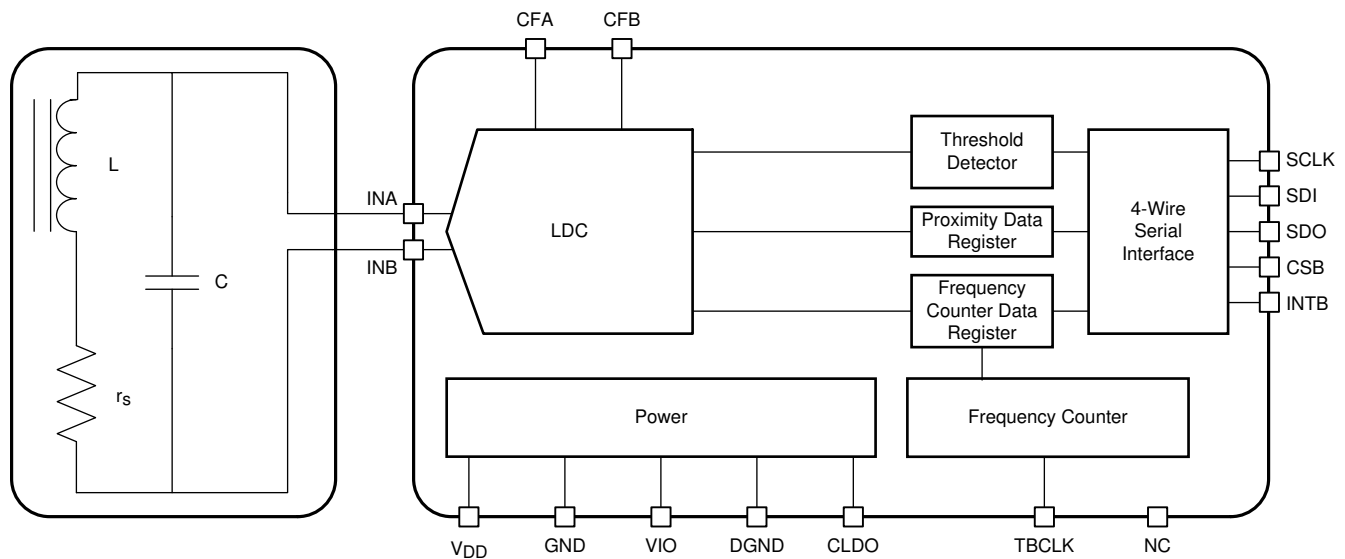
The LDC1001-Q1 device is an inductance-to-digital converter that simultaneously measures the impedance and resonant frequency of an LC resonator. The device accomplishes this task by regulating the oscillation amplitude in a closed-loop configuration to a constant level, while monitoring the energy dissipated by the resonator. By monitoring the amount of power injected into the resonator, the LDC1001-Q1 device can determine the value of R_p . When the value is determined, the device returns this as a digital value which is inversely proportional to R_p . In addition, the LDC1001-Q1 device also measure the oscillation frequency of the LC circuit. This frequency is used to determine the inductance of the LC circuit. The device outputs a digital value that is inversely proportional to frequency.

The threshold detector block provides a comparator with hysteresis. With the threshold registers programmed and comparator enabled, the proximity data register is compared with threshold registers and INTB pin indicates the output.

The device has a simple 4-wire SPI interface. The INTB pin provides multiple functions which are programmable with SPI.

The device has separate analog and I/O supplies. The analog supply operates at 5 V and the I/O operates at 1.8 to 5 V. The integrated LDO requires a 56-nF capacitor connected from the CLDO pin to GND.

7.2 Functional Block Diagram



7.3 Feature Description

7.3.1 Inductive Sensing

An alternating current (AC) flowing through a coil generates an AC magnetic field. If a conductive material, such as a metal target, is brought into the vicinity of the coil, this magnetic field induces circulating currents (eddy currents) on the surface of the target. These eddy currents are a function of the distance, size, and composition of the target. These eddy currents then generate a magnetic field that opposes the original field generated by the coil. This mechanism is best compared to a transformer, where the coil is the primary core and the eddy current is the secondary core. The inductive coupling between both cores depends on distance and shape. Hence the resistance and inductance of the secondary core (eddy current), shows up as a distant dependent resistive and inductive component on the primary side (coil). [Figure 5](#) through [Figure 8](#) show a simplified circuit model.

Feature Description (continued)

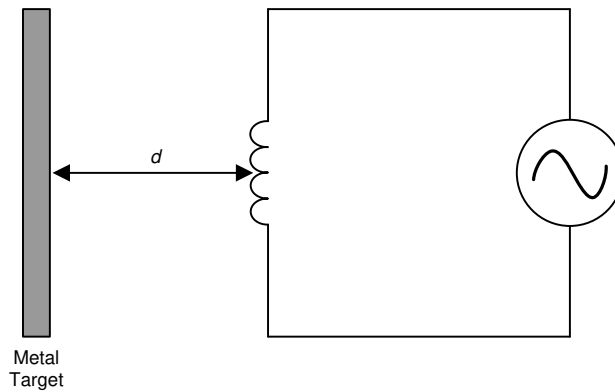


Figure 5. Inductor With a Metal Target

Eddy currents generated on the surface of the target can be modeled as a transformer as shown in Figure 6. The coupling between the primary and secondary coils is a function of the distance and characteristics of the conductor. In Figure 6, the inductance L_s is the inductance of the coil, and r_s is the parasitic series resistance of the coil. The inductance $L(d)$, which is a function of distance, d , is the coupled inductance of the metal target. Likewise, $R(d)$ is the parasitic resistance of the eddy currents.

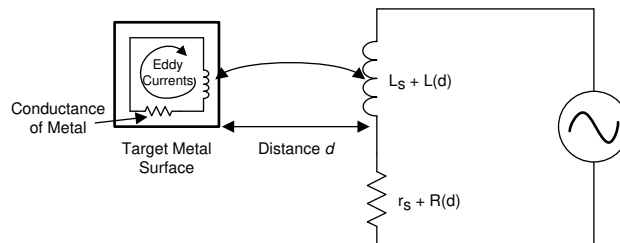


Figure 6. Metal Target Modeled as L and R With Circulating Eddy Currents

Generating an alternating magnetic field with just an inductor consumes a large amount of power. This power consumption can be reduced by adding a parallel capacitor, turning the right part of Figure 6 into a resonator as shown in Figure 7. In this manner the power consumption is reduced to the eddy and inductor losses $r_s + R(d)$ only.

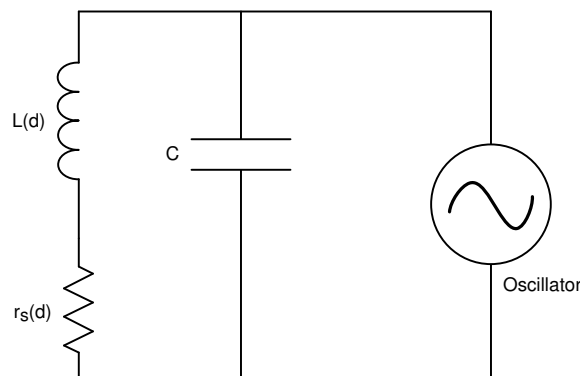
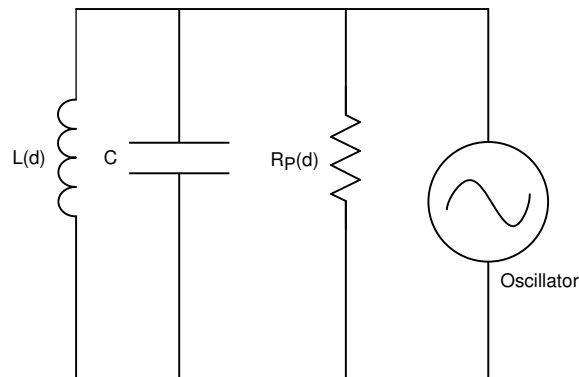


Figure 7. LC Tank Connected to Oscillator

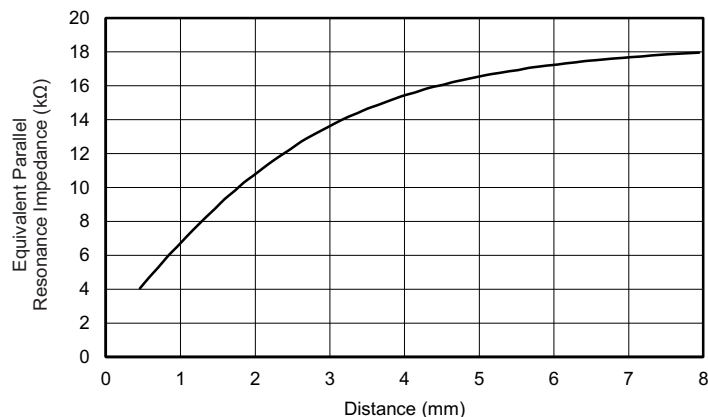
The LDC1001-Q1 device does not directly measure the series resistance. Instead, the device measures the equivalent parallel resonance impedance R_p (see Figure 8). This representation is equivalent to the representation shown in Figure 8, where the parallel resonance impedance $R_p(d)$ is given by Equation 1.

Feature Description (continued)

Figure 8. Equivalent Resistance of r_s in Parallel With LC Tank

$$R_p(d) = (1 / ([r_s + R(d)]) \times ([L_s + L(d)]) / C \quad (1)$$

$$R_p = (1 / r_s) \times (L / C) \quad (2)$$

Figure 9 shows the variation in R_p as a function of distance for a 14-mm diameter PCB coil (23 turns, 4-mil trace width, 4-mil spacing between trace, 1-oz copper thickness, FR4). The target metal used is a stainless steel 2-mm thick.


Figure 9. Typical R_p vs Distance With a 14-mm PCB Coil
7.3.2 Measuring Parallel Resonance Impedance and Inductance With LDC1001-Q1

Remember that the LDC1001-Q1 can determine the value of R_p by monitoring the amount of power injected into the resonator. The device returns this value as a digital value which is inversely proportional to R_p . The LDC1001-Q1 device can also measure the oscillation frequency of the LC circuit, which can be used to determine the inductance of the LC circuit. The oscillation frequency is returned as a digital value.

The LDC1001-Q1 device supports a wide range of LC combinations with oscillation frequencies ranging from 5 kHz to 5 MHz and R_p ranging from 798 Ω to 3.93 M Ω . This range of R_p can be viewed as the maximum input range of an ADC. As shown in Figure 9, the range of R_p is typically much smaller than maximum input range supported by the LDC1001-Q1 device. To achieve better resolution in the desired sensing range, the LDC1001-Q1 device offers a programmable input range through the R_{p_MIN} and R_{p_MAX} registers. See the [Calculation of \$R_{p_Min}\$ and \$R_{p_Max}\$](#) section for how to set these registers.

When the resonance impedance of the sensor, R_p , drops below the programmed R_{p_MIN} , the R_p output of the LDC will clip at the full scale output. An example occurrence of this situation is when a target comes too close to the coil.

Feature Description (continued)

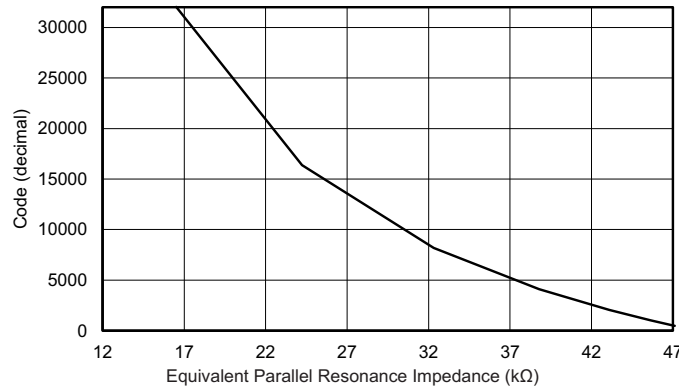


Figure 10. Transfer Characteristics of LDC1001-Q1 With Rp_MIN = 16.160 kΩ and Rp_MAX = 48.481 kΩ

Use Equation 3 to calculate the resonance impedance from the digital output code.

$$R_p = (R_{p_MAX} \times R_{p_MIN}) / (R_{p_MIN} \times (1 - Y) + R_{p_MAX} \times Y), \text{ in } \Omega.$$

Where:

- $Y = \text{Proximity Data} / 2^{15}$
- Proximity data is the LDC output, register address 0x21 and 0x22. (3)

Example: If Proximity data (address 0x22 to 0x21) is 5000, Rp_MIN is 2.394 kΩ, and Rp_MAX is 38.785 kΩ, the resonance impedance is given by:

$$Y = 5000 / 2^{15} = 0.1526 \quad (4)$$

$$R_p = (38785 \times 2394) / (2394 \times (1 - 0.1526) + 38785 \times 0.1526) = (92851290) / (2028.675 + 5918.591) \quad (5)$$

$$R_p = 11.683 \text{ k}\Omega \quad (6)$$

Figure 11 and Figure 12 show the change in RMS noise versus distance and a histogram of noise, with the target at an 0.8-mm distance from the sensor coil. Data was collected with a 14-mm PCB coil (23 turns, 4-mil trace width, 4-mil spacing between trace, 1-oz copper thickness, FR4) with a sensing range of 0.125 mm to 1.125 mm. At a distance of 0.8 mm, the RMS noise is approximately 250 nm.

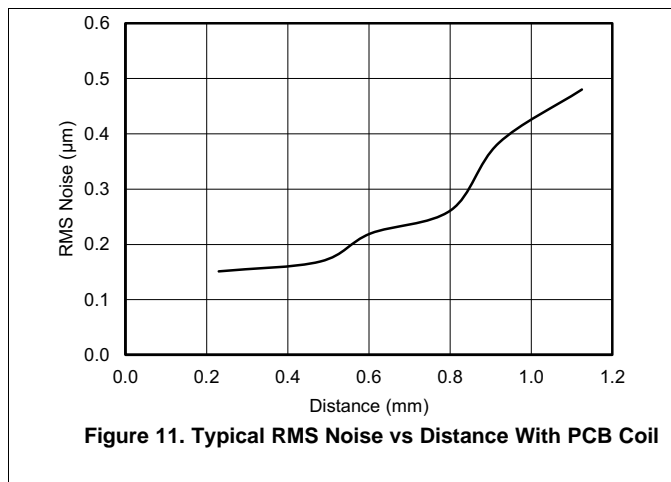


Figure 11. Typical RMS Noise vs Distance With PCB Coil

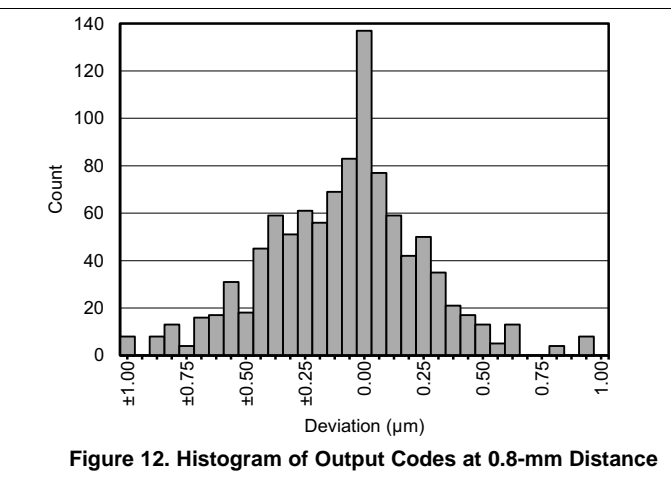


Figure 12. Histogram of Output Codes at 0.8-mm Distance

NOTE

Although the LDC1001-Q1 device has high resolution, the absolute accuracy depends on offset and gain correction which can be achieved by two-point calibration.

Feature Description (continued)

7.3.2.1 Measuring Inductance

The LDC1001-Q1 device measures the frequency of the oscillation of the sensor by a frequency counter. The frequency counter timing is set by an external clock applied on the TBCLK pin. The sensor resonance frequency is derived from the frequency-counter register value (see sections [Frequency Counter LSB \(offset = 0x23\) \[reset = NA\]](#) through [Frequency Counter MSB \(offset = 0x25\) \[reset = NA\]](#)) as shown in Equation 7.

$$f_{\text{sensor}} = (1/3) \times (f_{\text{ext}} / f_{\text{count}}) \times t_{\text{res}}$$

where

- f_{sensor} is the sensor frequency
- f_{ext} is the frequency of the external clock
- f_{count} is the value obtained from the Frequency Counter Data register (see the [Frequency Counter LSB \(offset = 0x23\) \[reset = NA\]](#) section through the [Frequency Counter MSB \(offset = 0x25\) \[reset = NA\]](#) section)
- t_{res} is the programmed response time (see the [LDC Configuration \(offset = 0x04\) \[reset = 0x1B\]](#) section) (7)

Use Equation 8 to calculate the inductance in H.

$$L = 1 / [C \times (2 \times \pi \times f_{\text{sensor}})^2]$$

where

- C is the parallel capacitance of the resonator (8)

7.3.2.1.1 Example

If $f_{\text{ext}} = 6 \text{ MHz}$, $t_{\text{res}} = 6144$, $C = 10 \text{ pF}$, and measured $f_{\text{count}} = 3000$ (decimal) (see sections [Frequency Counter LSB \(offset = 0x23\) \[reset = NA\]](#) through [Frequency Counter MSB \(offset = 0x25\) \[reset = NA\]](#)), then use Equation 9 to calculate sensor resonance frequency:

$$f_{\text{sensor}} = 1/3 \times (6000000 / 3000) \times (6144) = 4.096 \text{ MHz} \quad (9)$$

Now use Equation 10.

$$L = 1 / [C \times (2 \times \pi \times f_{\text{sensor}})^2]$$

where

- $L = 15.098 \text{ } \mu\text{H}$ (10)

NOTE

The accuracy of a measurement largely depends upon the frequency of the external time-base clock (TBCLK). A higher frequency will provide better measurement accuracy. The maximum supported frequency is 8 MHz.

7.4 Device Functional Modes

7.4.1 INTB Pin Modes

The INTB pin is a configurable output pin which can be used to drive an interrupt on an MCU. The LDC1001-Q1 device provides three different modes on the INTB pin which include:

1. Comparator mode
2. Wake-up mode
3. DRDY mode

The LDC1001-Q1 device has a built-in high trigger and low trigger threshold registers that can be a comparator with programmable hysteresis or a special mode that is used to wake up an MCU. The following sections describe these modes in detail.

7.4.1.1 Comparator Mode

In the comparator mode, the INTB pin is asserted or deasserted when the proximity register value increases above the threshold high registers or decreases below the threshold low registers, respectively. In this mode, the function of the LDC1001-Q1 device is a proximity switch with programmable hysteresis.

Device Functional Modes (continued)

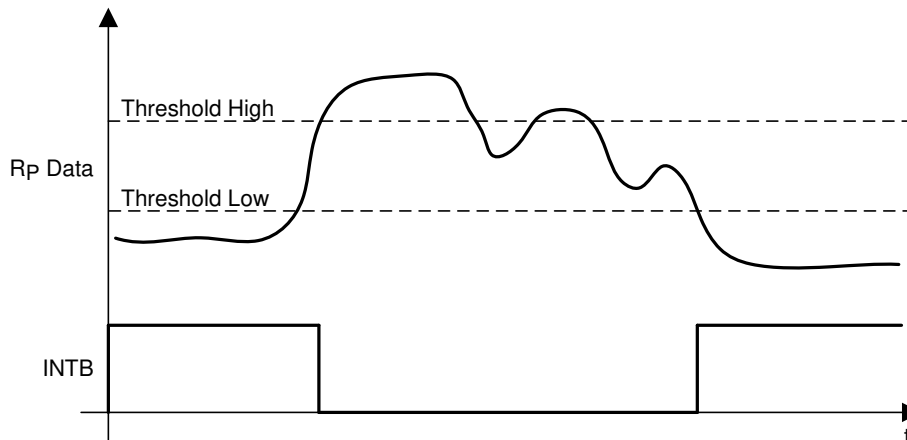


Figure 13. Behavior of the INTB Pin in Comparator Mode

7.4.1.2 Wake-Up Mode

In wake-up mode, the INTB pin is asserted when proximity register value increases above the threshold high registers and is deasserted when wake-up mode is disabled in the INTB pin mode register.

This mode can wake up an MCU that is in sleep mode to conserve power.

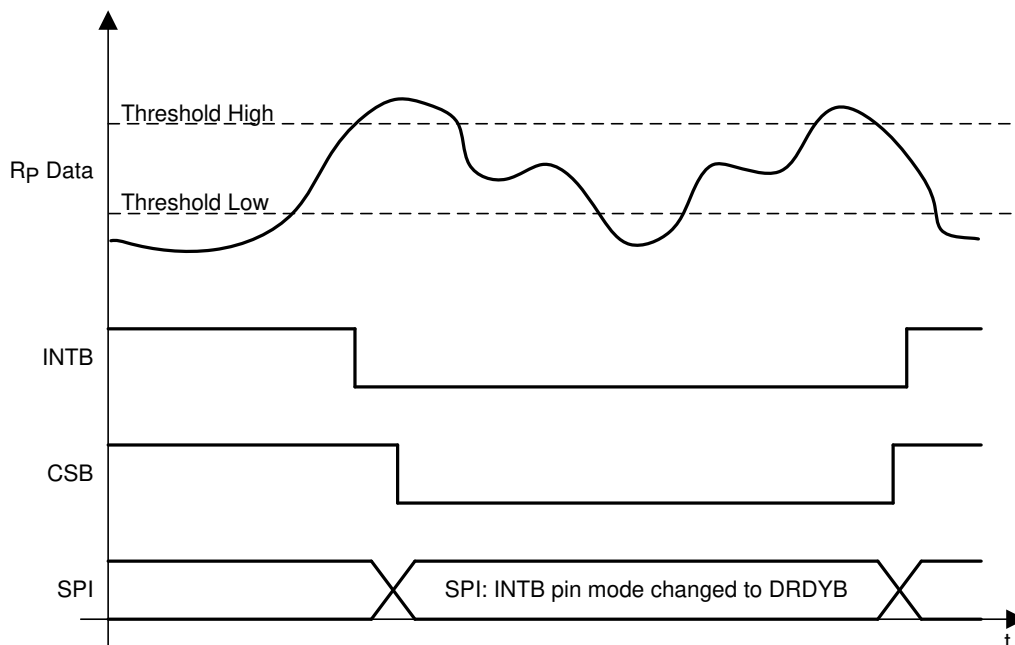
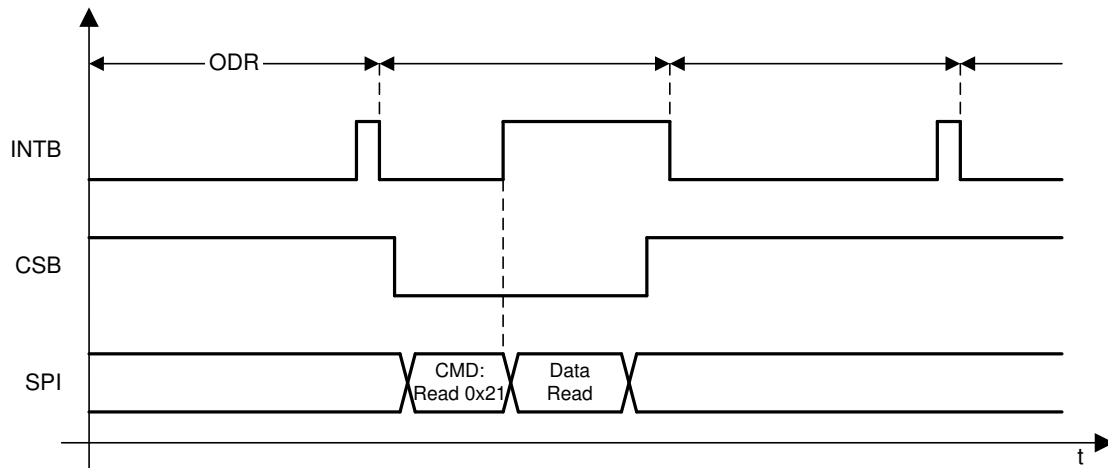


Figure 14. Behavior of the INTB Pin in Wake-Up Mode

7.4.1.3 DRDYB Mode

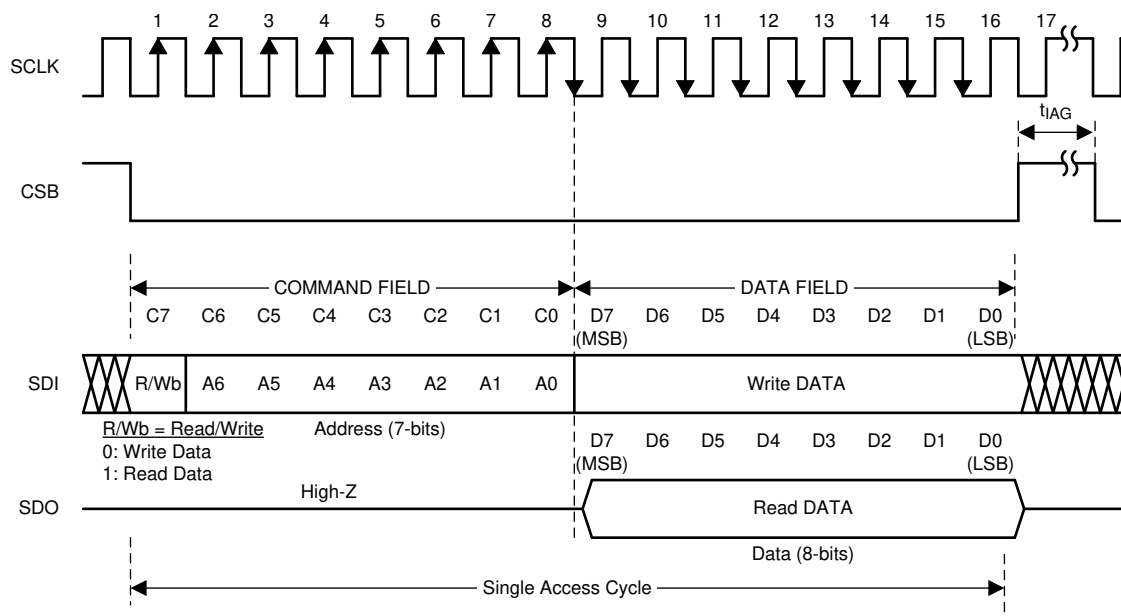
In DRDY mode (default), the INTB pin is asserted every time the conversion data is available and is deasserted when the read command on register 0x21 is registered internally. If the read command is in progress, the pin is pulsed instead.

Device Functional Modes (continued)

Figure 15. Behavior of the INTB Pin in DRDYB Mode
7.5 Programming
7.5.1 Digital Interface

The LDC1001-Q1 device uses a 4-wire SPI interface to access control and data registers. The LDC1001-Q1 device is an SPI slave device and does not initiate any transactions.

7.5.1.1 SPI Description

A typical serial interface transaction begins with an 8-bit instruction that is comprised of a read-write (R/W) bit (MSB, R = 1) and a 7-bit address of the register followed by a data field that is typically 8 bits. However, the data field can be extended to a multiple of 8 bits by providing sufficient SPI clocks. See the [Extended SPI Transactions](#) section.


Figure 16. Serial Interface Protocol

Programming (continued)

Each assertion of the chip select bar (CSB) begins a new register access. The R/W bit in the command field configures the direction of the access. A value of 0 indicates a write operation, and a value of 1 indicates a read operation. All output data is driven on the falling edge of the serial clock SCLK, and all input data is sampled on the rising edge of the serial clock SCLK. Data is written into the register on the rising edge of the 16th clock. Deasserting the CSB pin after the 16th clock is required. No data write occurs if the CSB pin is deasserted before the 16th clock.

7.5.1.2 Extended SPI Transactions

A transaction can be extended to multiple registers by keeping the CSB pin asserted beyond the stated 16 clocks. In this mode, the register addresses increment automatically. The CSB pin must be asserted during $8 \times (1 + N)$ clock cycles of SCLK, where N is the amount of bytes to write or read during the transaction.

During an extended read access, the SDO pin outputs register contents every 8 clock cycles after the initial 8 clocks of the command field. During an extended write access, the data is written to the registers every 8 clock cycles after the initial 8 clocks of the command field.

Extended transactions can be used to read 16 bits of proximity data and 24 bits of frequency data—all in one SPI transaction—by initiating a read from register 0x21.

7.6 Register Map

Table 1. Register Map⁽¹⁾⁽²⁾

REGISTER NAME	ADDRESS	TYPE ⁽³⁾	DEFAULT	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
Device ID	0x00	R	0x80	Device ID							
Rp_MAX	0x01	R/W	0x0E	Rp Maximum							
Rp_MIN	0x02	R/W	0x14	Rp Minimum							
Sensor Frequency	0x03	R/W	0x45	Min Resonating Frequency							
LDC Configuration	0x04	R/W	0x1B	Reserved (000)			Amplitude		Response Time		
Clock Configuration	0x05	R/W	0x01	Reserved (000000)						CLK_SEL	CLK_PD
Comparator Threshold High LSB	0x06	R/W	0xFF	Threshold High LSB							
Comparator Threshold High MSB	0x07	R/W	0xFF	Threshold High MSB							
Comparator Threshold Low LSB	0x08	R/W	0x00	Threshold Low LSB							
Comparator Threshold Low MSB	0x09	R/W	0x00	Threshold Low MSB							
INTB Pin Configuration	0x0A	R/W	0x00	Reserved (00000)					INTB_MODE		
Power Configuration	0x0B	R/W	0x00	Reserved (0000000)							PWR_MODE
Status	0x20	R		OSC Dead	DRDYB	Wake-up	Comparator	Don't Care			
Proximity Data LSB	0x21	R		Proximity Data[7-0]							
Proximity Data MSB	0x22	R		Proximity Data[15-8]							
Frequency Counter Data LSB	0x23	R		ODR LSB							
Frequency Counter Data Mid-Byte	0x24	R		ODR Mid Byte							
Frequency Counter Data MSB	0x25	R		ODR MSB							

(1) Values of bits which are unused should be set to default values only.

(2) LEGEND R/W = read/write. R = read only. W = write only

(3) When the device is in active mode (the PWR_MODE bit is SET), registers 0x01 through 0x05 are read only (R).

7.6.1 Register Description

7.6.1.1 Revision ID (offset = 0x00) [reset = 0x80]

Figure 17. Revision ID Register

7	6	5	4	3	2	1	0
Revision ID							
R							

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

Table 2. Revision ID Field Descriptions

Bit	Field	Type	Reset	Description
7-0	Revision ID	R	0x080	Revision ID of silicon.

7.6.1.2 Rp_MAX (offset = 0x01) [reset = 0x0E]
Figure 18. Rp_MAX Register

7	6	5	4	3	2	1	0
Rp Maximum							
R/W							

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

Table 3. Rp_MAX Field Descriptions

Bit	Field	Type	Reset	Description
7-0	Rp Maximum	R/W	0x0E	Maximum R_p that the LDC1001-Q1 device must measure. Configures the input dynamic range of the LDC1001-Q1 device. Register setting for Rp_MAX (k Ω): 0x00 = 3926.991 0x01 = 3141.593 0x02 = 2243.995 0x03 = 1745.329 0x04 = 1308.997 0x05 = 981.748 0x06 = 747.998 0x07 = 581.776 0x08 = 436.332 0x09 = 349.066 0x0A = 249.333 0x0B = 193.926 0x0C = 145.444 0x0D = 109.083 0x0E = 83.111 0x0F = 64.642 0x10 = 48.481 0x11 = 38.785 0x12 = 27.704 0x13 = 21.547 0x14 = 16.16 0x15 = 12.12 0x16 = 9.235 0x17 = 7.182 0x18 = 5.387 0x19 = 4.309 0x1A = 3.078 0x1B = 2.394 0x1C = 1.796 0x1D = 1.347 0x1E = 1.026 0x1F = 0.798

7.6.1.3 Rp_MIN (offset = 0x02) [reset = 0x14]
Figure 19. Rp_MIN Register

7	6	5	4	3	2	1	0
Rp Minimum							
R/W							

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

Table 4. Rp_MIN Field Descriptions

Bit	Field	Type	Reset	Description
7-0	Rp Minimum	R/W	0x014	<p>Minimum R_p that the LDC1001-Q1 device must measure. Configures the input dynamic range of the LDC1001-Q1 device.</p> <p>Register setting for Rp_MIN (kΩ):</p> <ul style="list-style-type: none"> 0x20 = 3926.991 0x21 = 3141.593 0x22 = 2243.995 0x23 = 1745.329 0x24 = 1308.997 0x25 = 981.748 0x26 = 747.998 0x27 = 581.776 0x28 = 436.332 0x29 = 349.066 0x2A = 249.333 0x2B = 193.926 0x2C = 145.444 0x2D = 109.083 0x2E = 83.111 0x2F = 64.642 0x30 = 48.481 0x31 = 38.785 0x32 = 27.704 0x33 = 21.547 0x34 = 16.16 0x35 = 12.12 0x36 = 9.235 0x37 = 7.182 0x38 = 5.387 0x39 = 4.309 0x3A = 3.078 0x3B = 2.394 0x3C = 1.796 0x3D = 1.347 0x3E = 1.026 0x3F = 0.798

7.6.1.4 Sensor Frequency (offset = 0x03) [reset = 0x45]

Figure 20. Sensor Frequency Register

7	6	5	4	3	2	1	0
Min Resonating Frequency							
R/W							

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

Table 5. Sensor Frequency Field Descriptions

Bit	Field	Type	Reset	Description
7-0	Min Resonating Frequency	R/W	0x45	<p>Sets the minimum resonating frequency to approximately 20% below the lowest resonating frequency of the sensor with no target in front. Use Equation 11 to determine the value of register.</p> $N = 68.94 \times \log_{10}(f / 2000)$ <p>where</p> <ul style="list-style-type: none"> N = Register Value. Round to nearest value. f = 20% below resonating frequency, Hz <p>(11)</p> <p>Example: Sensor frequency (f_{sensor}) = 1 MHz</p> $f = 0.8 \times 1 \text{ MHz} = 800 \text{ KHz}$ <p>(12)</p> $N = 68.94 \times \log_{10}(800 \text{ KHz} / 2000) = \text{Round to nearest whole number } (179.38) = 179 \text{ (Value to be programmed in the sensor frequency register)}$ <p>(13)</p>

7.6.1.5 LDC Configuration (offset = 0x04) [reset = 0x1B]

Figure 21. LDC Configuration Register

7	6	5	4	3	2	1	0
Reserved			Amplitude		Response Time		
—			R/W		R/W		

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

Table 6. LDC Configuration Field Descriptions

Bit	Field	Type	Reset	Description
7-5	Reserved	—	—	Reserved to 0
4-3	Amplitude	R/W	0x1B	<p>Sets the oscillation amplitude</p> <p>00: 1 V</p> <p>01: 2 V</p> <p>10: 4 V</p> <p>11: Reserved</p>
2-0	Response Time	R/W	0x1B	<p>Sets the response time</p> <p>000: Reserved</p> <p>001: Reserved</p> <p>010: 192</p> <p>011: 384</p> <p>100: 768</p> <p>101: 1536</p> <p>110: 3072</p> <p>111: 6144</p>

7.6.1.6 Clock Configuration (offset = 0x05) [reset = 0x01]
Figure 22. Clock Configuration Register

7	6	5	4	3	2	1	0
Reserved						CLK_SEL	CLK_PD
R/W						R/W	R/W

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

Table 7. Clock Configuration Field Descriptions

Bit	Field	Type	Reset	Description
7-2	Reserved	—	—	Reserved to 0
1	CLK_SEL	R/W	0x01	<p>1: Do not use</p> <p>0: External time-base clock used for frequency counter (TBCLK).</p>
0	CLK_PD	R/W	0x01	<p>1: Disable external time base clock (for lower power consumption in standby mode)</p> <p>0: Enable External time base clock.</p>

7.6.1.7 Comparator Threshold High LSB (offset = 0x06) [reset = 0xFF]
Figure 23. Comparator Threshold High LSB Register

7	6	5	4	3	2	1	0
Threshold High[7:0]	Threshold High[6]	Threshold High[5]	Threshold High[4]	Threshold High[3]	Threshold High[2]	Threshold High[1]	Threshold High[0]
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

Table 8. Comparator Threshold High LSB Field Descriptions

Bit	Field	Type	Reset	Description
7:0	Threshold High LSB Threshold High[7:0]	R/W	0xFF	Least Significant byte (LSB) of the threshold high register. This register is a buffer. A read reflects the current value of the threshold high[7:0] register. See the Comparator Threshold High MSB (offset = 0x07) [reset = 0xFF] section for details on updating the threshold high register.

7.6.1.8 Comparator Threshold High MSB (offset = 0x07) [reset = 0xFF]
Figure 24. Comparator Threshold High MSB Register

7	6	5	4	3	2	1	0
Threshold High[15]	Threshold High[14]	Threshold High[13]	Threshold High[12]	Threshold High[11]	Threshold High[10]	Threshold High[9]	Threshold High[8]
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

Table 9. Comparator Threshold High MSB Field Descriptions

Bit	Field	Type	Reset	Description
7:0	Threshold High MSB Threshold High[15:8]	R/W	0xFF	Most significant byte (MSB) of the threshold high register. A write to this register copies the contents of the 0x06 register and writes to the threshold high register[15:0]. A read returns the threshold high [15:8] register. To update the threshold high register write register 0x06 first and then 0x07.

7.6.1.9 Comparator Threshold Low LSB (offset = 0x08) [reset = 0x00]
Figure 25. Comparator Threshold Low LSB Register

7	6	5	4	3	2	1	0
Threshold Low[7:0]	Threshold Low[6]	Threshold Low[5]	Threshold Low[4]	Threshold Low[3]	Threshold Low[2]	Threshold Low[1]	Threshold Low[0]
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

Table 10. Comparator Threshold Low LSB Field Descriptions

Bit	Field	Type	Reset	Description
7:0	Threshold Low LSB Threshold Low[7:0]	R/W	0x00	Least significant byte of the threshold low value. This register is a buffer. A read reflects the current value of the threshold low [7:0] register. See the Comparator Threshold Low MSB (offset = 0x09) [reset = 0x00] section for details on updating the threshold low register.

7.6.1.10 Comparator Threshold Low MSB (offset = 0x09) [reset = 0x00]
Figure 26. Comparator Threshold Low MSB Register

7	6	5	4	3	2	1	0
Threshold Low[15]	Threshold Low[14]	Threshold Low[13]	Threshold Low[12]	Threshold Low[11]	Threshold Low[10]	Threshold Low[9]	Threshold Low[8]
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

Table 11. Comparator Threshold Low MSB Field Descriptions

Bit	Field	Type	Reset	Description
7:0	Threshold Low MSB Threshold Low[15:8]	R/W	0x00	Most significant byte of the threshold low register. A write to this register copies the contents of the 0x08 register and writes to the threshold low register[15:0]. A read returns the threshold low [15:8] register. To update the threshold low register write register address 0x08 first and then 0x09.

7.6.1.11 INTB Pin Configuration (offset = 0x0A) [reset = 0x00]
Figure 27. INTB Pin Configuration Register

7	6	5	4	3	2	1	0
Reserved						Mode	
—						R/W	

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

Table 12. INTB Pin Configuration Field Descriptions

Bit	Field	Type	Reset	Description
7:3	Reserved	—	—	Reserved to 0
2:0	Mode	R/W	0x00	100: DRDYB enabled on the INTB pin 010: The INTB pin indicates the status of the comparator output 001: Wake-up enabled on the INTB pin 000: All modes disabled All other combinations are reserved

7.6.1.12 Power Configuration (offset = 0x0B) [reset = 0x00]
Figure 28. Power Configuration Register

7	6	5	4	3	2	1	0
Reserved							PWR_MODE
—							R/W

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

Table 13. Power Configuration Field Descriptions

Bit	Field	Type	Reset	Description
7:1	Reserved	—	—	Reserved to 0
0	PWR_MODE	R/W	0x00	0: Stand-by mode 1: Active mode. Conversion is enabled

7.6.1.13 Status (offset = 0x20) [reset = NA]
Figure 29. Status Register

7	6	5	4	3	2	1	0
OSC status	Data Ready	Wake-up	Comparator	Don't Care			
R	R	R	R	R			

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

Table 14. Status Field Descriptions

Bit	Field	Type	Reset	Description
7	OSC status	R	NA	1: Indicates that the oscillator is overloaded and has stopped 0: Oscillator is working
6	Data Ready	R	NA	0: Data is ready to be read 1: No new data is available
5	Wake-up	R	NA	0: Wake-up triggered. Proximity data is more than the threshold high value. 1: Wake-up is disabled
4	Comparator	R	NA	0: Proximity data is more than the threshold high value 1: Proximity data is less than the threshold low value
3:0	Don't Care	R	NA	

7.6.1.14 Proximity Data LSB (offset = 0x21) [reset = NA]
Figure 30. Proximity Data LSB Register

7	6	5	4	3	2	1	0
Proximity Data[7]	Proximity Data[6]	Proximity Data[5]	Proximity Data[4]	Proximity Data[3]	Proximity Data[2]	Proximity Data[1]	Proximity Data[0]
R	R	R	R	R	R	R	R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

Table 15. Proximity Data LSB Field Descriptions

Bit	Field	Type	Reset	Description
7:0	Proximity Data[7:0]	R	NA	Least significant byte of proximity data

7.6.1.15 Proximity Data MSB (offset = 0x22) [reset = NA]
Figure 31. Proximity Data MSB Register

7	6	5	4	3	2	1	0
Proximity Data[15]	Proximity Data[14]	Proximity Data[13]	Proximity Data[12]	Proximity Data[11]	Proximity Data[10]	Proximity Data[9]	Proximity Data[8]
R	R	R	R	R	R	R	R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

Table 16. Proximity Data MSB Field Descriptions

Bit	Field	Type	Reset	Description
7:0	Proximity data[15:8]	R	NA	Most significant byte of proximity data

7.6.1.16 Frequency Counter LSB (offset = 0x23) [reset = NA]
Figure 32. Frequency Counter LSB Register

7	6	5	4	3	2	1	0
ODR[7]	ODR[6]	ODR[5]	ODR[4]	ODR[3]	ODR[2]	ODR[1]	ODR[0]
R	R	R	R	R	R	R	R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

Table 17. Frequency Counter LSB Field Descriptions

Bit	Field	Type	Reset	Description
7:0	ODR LSB ODR[7:0]	R	NA	LSB of output data rate. Sensor frequency can be calculated using the output data rate. See the Measuring Inductance section.

7.6.1.17 Frequency Counter Mid-Byte (offset = 0x24) [reset = NA]
Figure 33. Frequency Counter Mid-Byte Register

7	6	5	4	3	2	1	0
ODR[15]	ODR[14]	ODR[13]	ODR[12]	ODR[11]	ODR[10]	ODR[9]	ODR[8]
R	R	R	R	R	R	R	R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

Table 18. Frequency Counter Mid-Byte Field Descriptions

Bit	Field	Type	Reset	Description
7:0	ODR Mid byte ODR[15:8]	R	NA	Middle byte of output data rate

7.6.1.18 Frequency Counter MSB (offset = 0x25) [reset = NA]
Figure 34. Frequency Counter MSB Register

7	6	5	4	3	2	1	0
ODR[23]	ODR[22]	ODR[21]	ODR[20]	ODR[19]	ODR[18]	ODR[17]	ODR[16]
R	R	R	R	R	R	R	R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

Table 19. Frequency Counter MSB Field Descriptions⁽¹⁾

Bit	Field	Type	Reset	Description
7:0	ODR MSB ODR[23:16]	R	NA	MSB of Output data rate

- (1) Take care to ensure that the proximity data[15:0] and Frequency Counter[23:0] registers are all from same conversion. Conversion data is updated to these registers only when a read is initiated on 0x21 register. If the read is delayed between subsequent conversions, these registers are not updated until another read is initiated on 0x21.

8 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

8.1.1 Calculation of Rp_Min and Rp_Max

Different sensing applications may have different ranges of the resonance impedance R_p to measure. The LDC1001-Q1 measurement range of R_p is controlled by setting two registers: Rp_MIN and Rp_MAX. For a given application, R_p must never be outside the range set by these register values, otherwise the measured value will be clipped. For optimal sensor resolution, the range of Rp_MIN to Rp_MAX should not be unnecessarily large. The following procedure is recommended to determine the Rp_MIN and Rp_MAX register values.

8.1.1.1 Rp_MAX

Rp_MAX sets the upper limit of the LDC1001-Q1 resonant impedance input range.

- Configure the sensor such that the eddy-current losses are minimized. As an example, for a proximity sensing application, set the distance between the sensor and the target to the maximum sensing distance.
- Measure the resonant impedance R_p using an impedance analyzer.
- Multiply R_p by 2 and use the next higher value from the register settings listed in [Table 3](#).

For example, if R_p is measured at 18 k Ω , $18000 \times 2 = 36000$. Referring to [Table 3](#), 38.785 k Ω is the smallest value larger than 36 k Ω , therefore Rp_MAX should be set to 0x11.

Setting Rp_MAX to a value not listed in [Table 3](#) can result in indeterminate behavior.

8.1.1.2 Rp_MIN

Rp_MIN sets the lower limit of the LDC1001-Q1 resonant impedance input range.

- Configure the sensor such that the eddy current losses are maximized. As an example, for a proximity sensing application, set the distance between the sensor and the metal target to the minimum sensing distance.
- Measure the resonant impedance R_p using an impedance analyzer.
- Divide the R_p value by 2 and then select the next lower R_p value from the register settings listed in [Table 4](#).

For example, if R_p at 1 mm is measured to be 5 k Ω , $5000 / 2 = 2500$. Referring to [Table 4](#), 2.394 k Ω is the smallest value smaller than 2.5 k Ω , which corresponds to an Rp_MIN value of 0x3B.

Setting Rp_MIN to a value not listed on [Table 4](#) can result in indeterminate behavior. In addition, Rp_MIN powers on with a default value of 0x14 which must be set to a value from [Table 4](#) prior to powering on the LDC.

8.1.2 Output Data Rate

The output data rate of the LDC1001-Q1 device depends on the sensor frequency, f_{sensor} and the Response Time[2-0] field in the LDC configuration register (address: 0x04).

$$\text{Output data rate} = f_{\text{sensor}} / (\text{Response Time}[2-0] / 3) \text{ in SPS (samples per second)} \quad (14)$$

8.1.2.1 Example

If $f_{\text{sensor}} = 5 \text{ MHz}$ and Response Time[2-0] = 192, then:

$$\text{Output data rate} = 5 \text{ MHz} / (192 / 3) = 78.125 \text{ KSPS} \quad (15)$$

Application Information (continued)

8.1.3 Selecting a Filter Capacitor (CFA and CFB Pins)

The filter capacitor is critical to the operation of the LDC1001-Q1 device. The capacitor should be low leakage, temperature stable, and it must not generate any piezoelectric noise (the dielectrics of many capacitors exhibit piezoelectric characteristics and any such noise is coupled directly through R_p into the converter). The optimal capacitance values range from 20 pF to 100 nF. The value of the capacitor is based on the time constant and resonating frequency of the LC tank.

If a ceramic capacitor is used, then a C0G (or NP0) grade dielectric is recommended. The voltage rating should be 10 V or higher. The traces connecting the CFA and CFB pins to the capacitor should be as short as possible to minimize any parasitics.

For optimal performance, the selected filter capacitor connected between the CFA and CFB pins must be as small as possible, but large enough such that the active filter does not saturate. The size of this capacitor depends on the time constant of the sense coil, which is given by L / r_s (L = inductance, r_s = series resistance of the inductor at oscillation frequency). The larger this time constant, the larger filter capacitor is required. Therefore the time constant reaches the maximum when there is no target present in front of the sensing coil.

Use the following procedure to find the optimal filter capacitance:

1. Use with a large filter capacitor. For a ferrite core coil, a value of 10 nF is generally large enough. For an air coil or PCB coil, a value of 100 pF is generally large enough.
2. Power on the LDC and set the desired register values.
3. Minimize the eddy currents losses by ensuring maximum clearance between the target and the sensing coil.
4. Observe the signal on the CFB pin using a scope. Because this node is very sensitive to capacitive loading, the use of an active probe is recommended. As an alternative, a passive probe with a 1-k Ω series resistance between the tip and the CFB pin can be used.
5. Vary the values of the filter capacitor until the signal observed on the CFB pin has an amplitude of approximately 1 V_{pp} . This signal scales linearly with the reciprocal of the filter capacitance. For example, if a 100-pF filter capacitor is applied and the signal observed on the CFB pin has a peak-to-peak value of 200 mV, the desired 1- V_{pp} value is obtained using a filter capacitor value that is calculated in [Equation 16](#).

$$200 \text{ mV} / 1 \text{ V} \times 100 \text{ pF} = 20 \text{ pF} \quad (16)$$

8.2 Typical Application

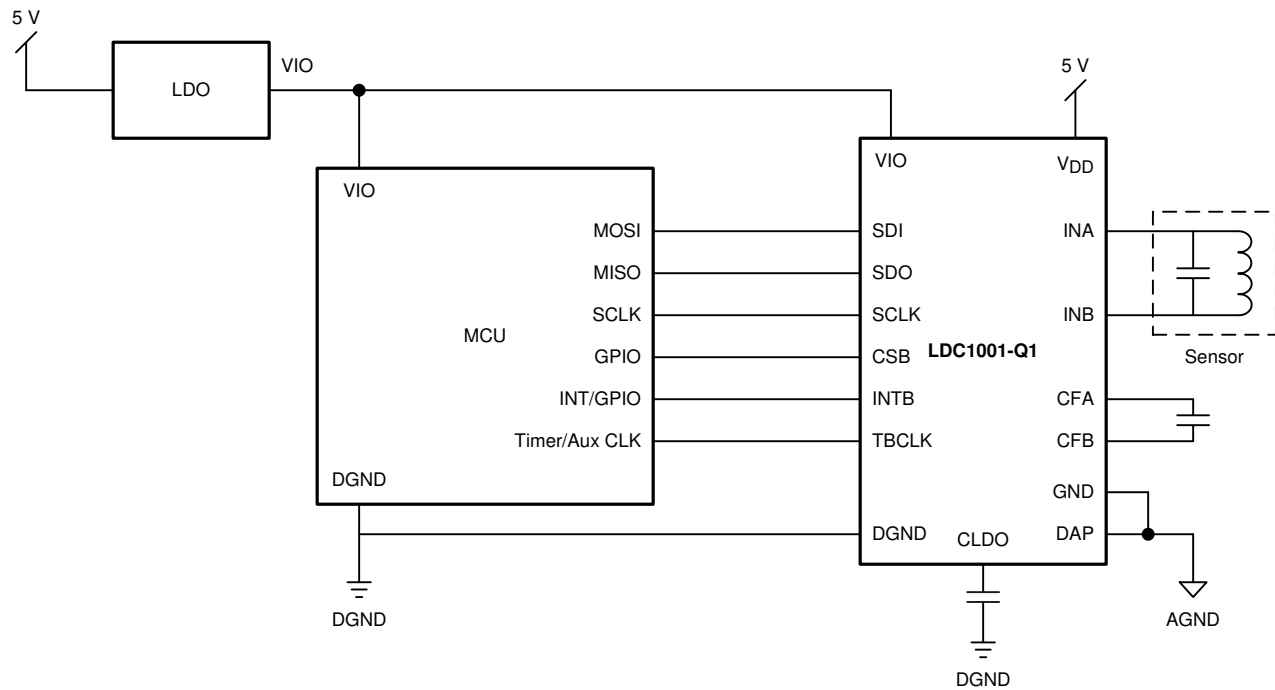


Figure 35. Typical Application Schematic

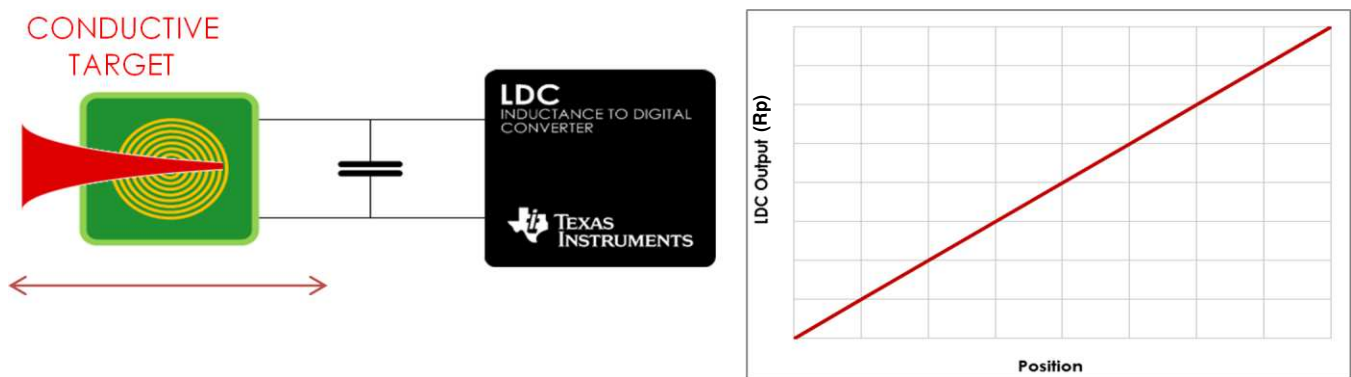


Figure 36. Linear Position Sensing

Typical Application (continued)

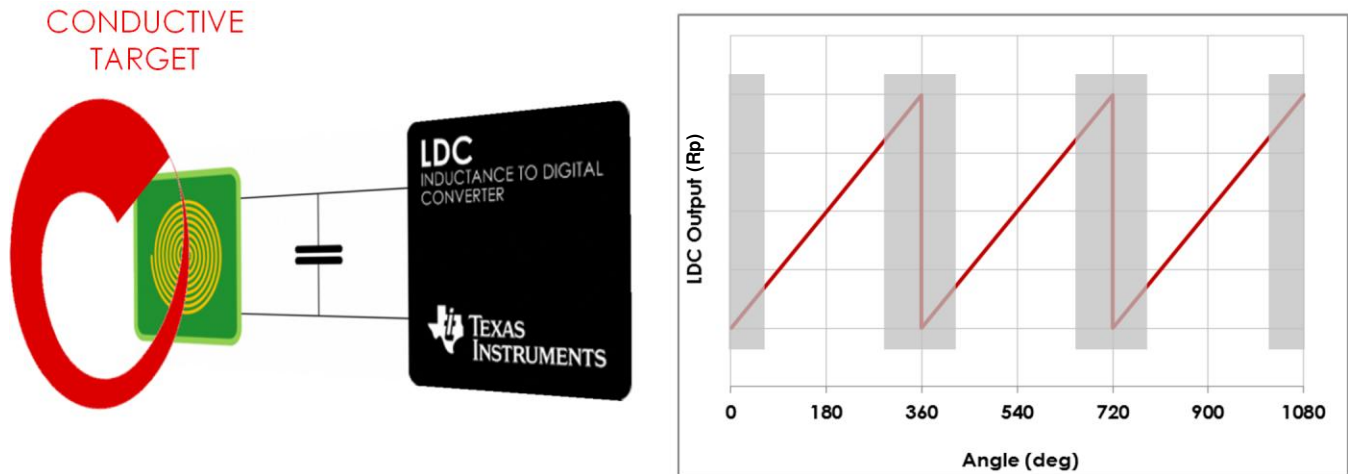


Figure 37. Angular Position Sensing

8.2.1 Design Requirements

For this design example, use the design parameters listed in Table 20 as the input parameters.

Table 20. Design Parameters

DESIGN PARAMETER	EXAMPLE VALUE
Minimum sensing distance	1 mm
Maximum sensing distance	8 mm
Output data rate	78 KSPS (Max data rate with LDC10xx series)
Number of PCB layers for sensor	2 layers

8.2.2 Detailed Design Procedure

8.2.2.1 Sensor and Target

In this example, consider a sensor with the characteristics listed in Table 21.

Table 21. Sensor Characteristics

PARAMETER	VALUE
Layers	2
Thickness of copper	1 oz
Coil shape	Circular
Number of turns	23
Trace thickness	4 mil
Trace spacing	4 mil
PCB core material	FR4
R _P at 1 mm	5 kΩ
R _P at 8 mm	12.5 kΩ
Nominal Inductance	18 μH

The target material used is stainless steel.

8.2.2.2 Calculating a Sensor Capacitor

Sensor frequency depends on various factors in the application. In this example, use [Equation 17](#) to calculate the sensor frequency to achieve an output data rate of 78 KSPS per the design parameter.

$$\text{Output Data Rate} = \frac{f_{\text{sensor}}}{\left(\frac{\text{Response time}}{3}\right)} \quad (17)$$

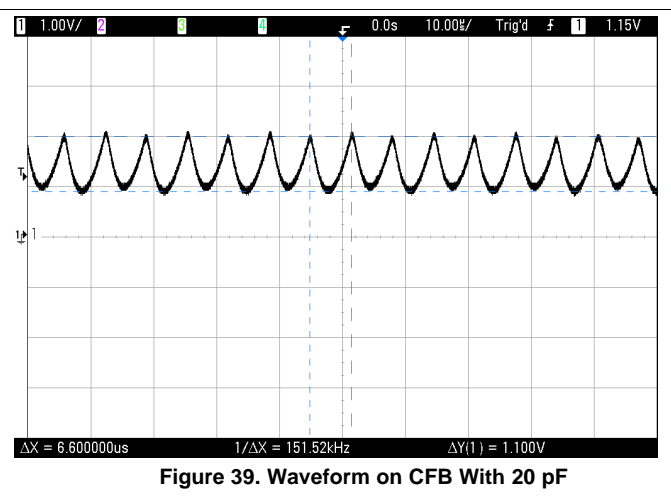
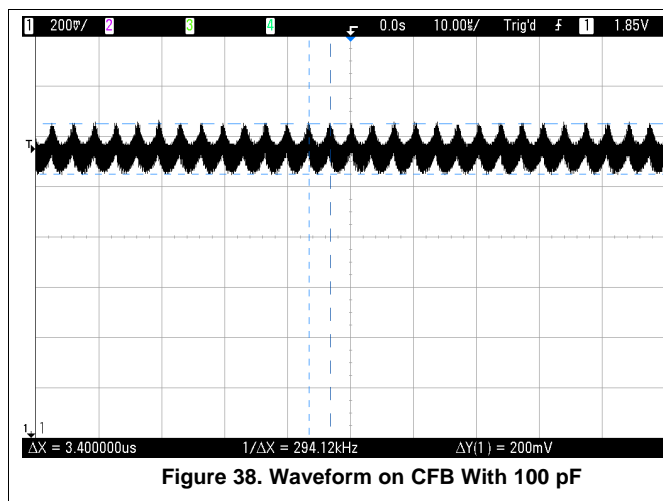
With the lowest response time (t_{res}) of 192 and output data rate of 78 KSPS, the calculated sensor frequency using [Equation 17](#) is 4.99 MHz.

Use [Equation 18](#) to calculate the sensor capacitor as 55 pF with a sensor inductance of 18 μH .

$$L = \frac{1}{C \times (2\pi \times f_{\text{sensor}})^2} \quad (18)$$

8.2.2.3 Selecting a Filter Capacitor

Use the steps listed in the [Selecting a Filter Capacitor \(CFA and CFB Pins\)](#) section to calculate a filter capacitor. For this example, the selected capacitor value is 20 pF. The following waveforms were taken on the CFB pin with a 14-mm, 2-layer PCB coil (23 turns, 4-mil trace width, 4-mil spacing between trace, 1-oz copper thickness, FR4).



8.2.2.4 Setting Rp_MIN and Rp_MAX

To calculate the value for the Rp_MAX register, use the following value: Rp at 8 mm is 12.5 k Ω , 12500 \times 2 = 25000. Then 27.704 k Ω is the nearest value larger than 25 k Ω . Referring to [Table 3](#), this value corresponds to a Rp_MAX value of 0x12.

To calculate the value for the Rp_MIN register, use the following value: Rp at 1 mm is 5 k Ω , 5000 / 2 = 2500. Then 2.394 k Ω is the nearest value lower than 2.5 k Ω . Referring to [Table 4](#), this value corresponds to Rp_MIN value of 0x3B.

8.2.2.5 Calculating Minimum Sensor Frequency

Use [Equation 19](#) to calculate the minimum sensor frequency.

$$N = 68.94 \times \log_{10} \left(\frac{F}{2500} \right)$$

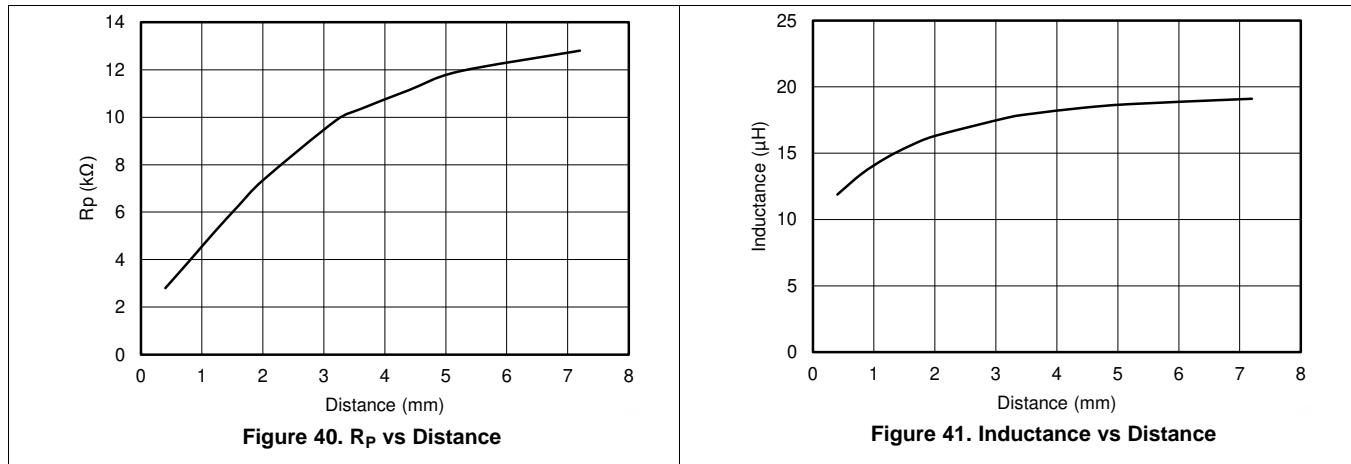
where

- N is 227.51

(19)

For this example, round the value of N up to 228. This value must be written into the watchdog timer register, which is used to wake up the internal circuit when the sensor is saturated.

8.2.3 Application Curves



9 Power Supply Recommendations

The LDC1001-Q1 device is designed to operate from an analog supply range of 4.75 V to 5.25 V and digital I/O supply range of 1.8 to 5.25 V. The analog supply voltage should be greater than or equal to the digital supply voltage for proper operation of the device. The supply voltage should be well regulated. If the supply is placed more than a few inches from the LDC1001-Q1 device, additional bulk capacitance may be required in addition to the ceramic bypass capacitors.

10 Layout

10.1 Layout Guidelines

Use the following guidelines:

- Bypass the V_{DD} and VIO pin to ground with a low-ESR ceramic bypass capacitor. A ceramic X7R dielectric capacitor with a value of 0.1 μF is recommend.
- Place the VDD, VIO, GND, and DGND pins as close to the device as possible. Take care to minimize the loop area formed by the bypass capacitor connection and the V_{DD} , VIO, GND, and DGND pins of the IC. See [Figure 42](#) for a PCB layout example.
- Bypass the CLDO pin to the digital ground (DGND) with a ceramic bypass capacitor with a value of 56 nF.
- Connect the filter capacitor that is selected using the procedure listed in the [Selecting a Filter Capacitor \(CFA and CFB Pins\)](#) section between the CFA and CFB pins. Place the capacitor close to the CFA and CFB pins. Do not use any ground or power planes below the capacitor and the trace connecting the capacitor and the CFx pins.
- Use two separate ground planes for the ground (GND) and digital ground (DGND) for a star connection as recommended. See [Figure 42](#) for a PCB layout example.

10.2 Layout Example

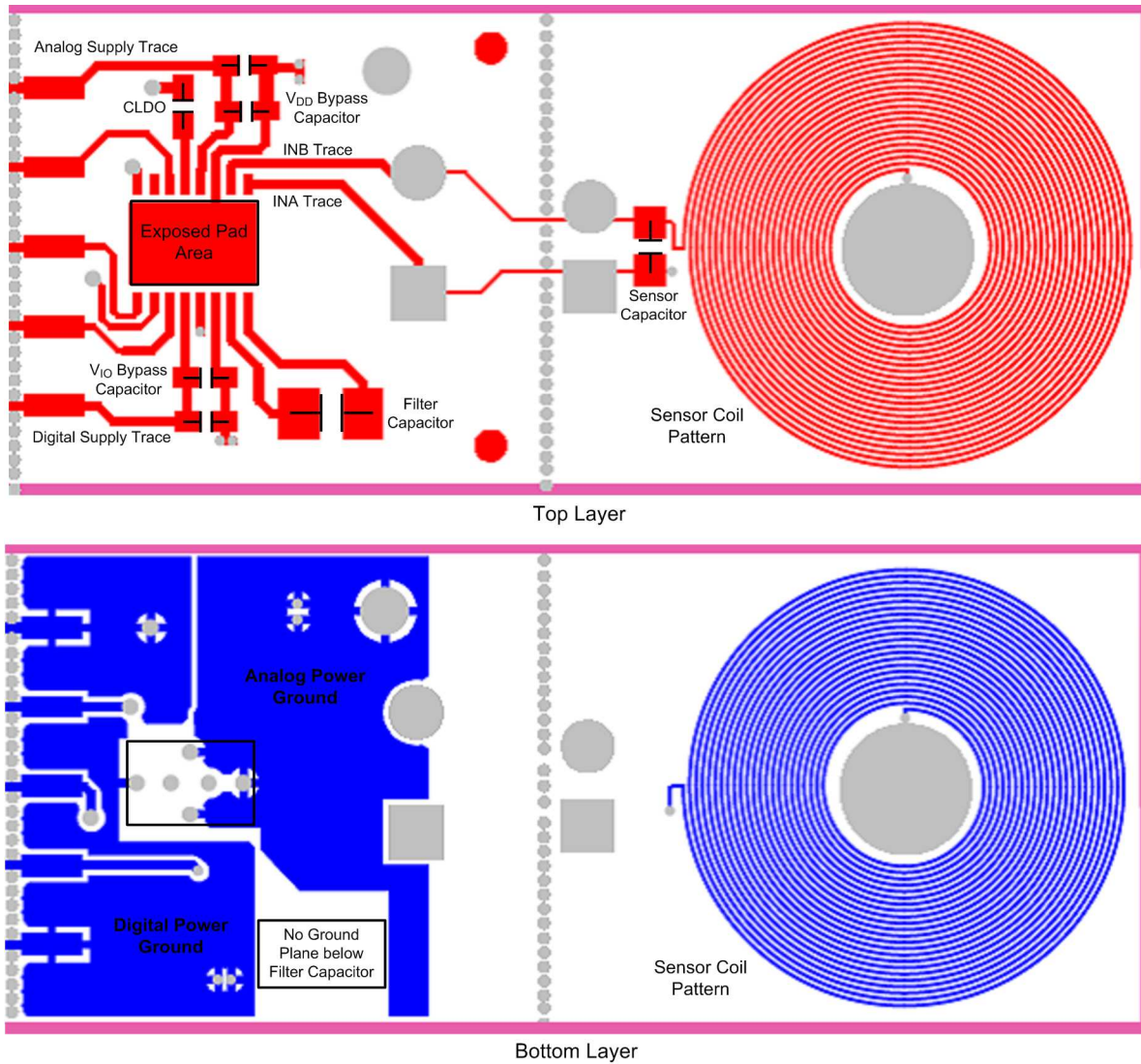


Figure 42. LDC10xx Board Layout

11 器件和文档支持

11.1 接收文档更新通知

要接收文档更新通知，请导航至 ti.com 上的器件产品文件夹。单击右上角的通知我进行注册，即可每周接收产品信息更改摘要。有关更改的详细信息，请查看任何已修订文档中包含的修订历史记录。

11.2 支持资源

TI E2E™ support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

Linked content is provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

11.3 商标

E2E is a trademark of Texas Instruments.
All other trademarks are the property of their respective owners.

11.4 静电放电警告



ESD 可能会损坏该集成电路。德州仪器 (TI) 建议通过适当的预防措施处理所有集成电路。如果不遵守正确的处理措施和安装程序，可能会损坏集成电路。

ESD 的损坏小至导致微小的性能降级，大至整个器件故障。精密的集成电路可能更容易受到损坏，这是因为非常细微的参数更改都可能会导致器件与其发布的规格不相符。

11.5 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

12 机械、封装和可订购信息

以下页面包含机械、封装和可订购信息。这些信息是指定器件的最新可用数据。数据如有变更，恕不另行通知，且不会对此文档进行修订。如需获取此数据表的浏览器版本，请查阅左侧的导航栏。

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
LDC1001EPWRQ1	ACTIVE	TSSOP	PW	16	2500	RoHS & Green	SN	Level-3-260C-168 HR	-40 to 150	LDC1001E	Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "-" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

TAPE AND REEL INFORMATION

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE


*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LDC1001EPWRQ1	TSSOP	PW	16	2500	330.0	12.4	6.95	5.6	1.6	8.0	12.0	Q1

TAPE AND REEL BOX DIMENSIONS


*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LDC1001EPWRQ1	TSSOP	PW	16	2500	356.0	356.0	35.0



NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.
4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
5. Reference JEDEC registration MO-153.

EXAMPLE BOARD LAYOUT

PW0016A

TSSOP - 1.2 mm max height

SMALL OUTLINE PACKAGE



LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE: 10X



SOLDER MASK DETAILS

4220204/A 02/2017

NOTES: (continued)

- 6. Publication IPC-7351 may have alternate designs.
- 7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

EXAMPLE STENCIL DESIGN

PW0016A

TSSOP - 1.2 mm max height

SMALL OUTLINE PACKAGE



SOLDER PASTE EXAMPLE
BASED ON 0.125 mm THICK STENCIL
SCALE: 10X

4220204/A 02/2017

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

重要声明和免责声明

TI“按原样”提供技术和可靠性数据（包括数据表）、设计资源（包括参考设计）、应用或其他设计建议、网络工具、安全信息和其他资源，不保证没有瑕疵且不做任何明示或暗示的担保，包括但不限于对适销性、某特定用途方面的适用性或不侵犯任何第三方知识产权的暗示担保。

这些资源可供使用 TI 产品进行设计的熟练开发人员使用。您将自行承担以下全部责任：(1) 针对您的应用选择合适的 TI 产品，(2) 设计、验证并测试您的应用，(3) 确保您的应用满足相应标准以及任何其他功能安全、信息安全、监管或其他要求。

这些资源如有变更，恕不另行通知。TI 授权您仅可将这些资源用于研发本资源所述的 TI 产品的应用。严禁对这些资源进行其他复制或展示。您无权使用任何其他 TI 知识产权或任何第三方知识产权。您应全额赔偿因在这些资源的使用中对 TI 及其代表造成的任何索赔、损害、成本、损失和债务，TI 对此概不负责。

TI 提供的产品受 [TI 的销售条款](#) 或 [ti.com](#) 上其他适用条款/TI 产品随附的其他适用条款的约束。TI 提供这些资源并不会扩展或以其他方式更改 TI 针对 TI 产品发布的适用的担保或担保免责声明。

TI 反对并拒绝您可能提出的任何其他或不同的条款。

邮寄地址：Texas Instruments, Post Office Box 655303, Dallas, Texas 75265

Copyright © 2022，德州仪器 (TI) 公司