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으리

LM3533 用于智能手机的完整照明电源解决方案

Technical [Documents](http://www.ti.com.cn/product/cn/LM3533?dcmp=dsproject&hqs=td&#doctype2)

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-
-
- 可选择带有 128 个可编程增益设置电阻的模拟环境 图案对其输出电流进行调制。 光传感器 (ALS) 输入或者带有内部低通滤波器的脉
-
-
-
-
- 完全可编程 LED 分组和控制
- 4个可配置过压保护阈值(16V, 24V, 32V 和) 件采用
-
-

2 应用范围 器件信息^{[\(1\)](#page-0-0)}

- 用于智能手机照明的电源
- 显示器、键区和指示器照明
-

1 特性 **3** 说明

Tools & **[Software](http://www.ti.com.cn/product/cn/LM3533?dcmp=dsproject&hqs=sw&#desKit)**

¹• 驱动两个并联高电压发光二极管 (LED) 灯串为显示 LM3533 是一款用于智能手机内背光、键盘和指示器 屏和键盘提供照明 LED 的完整电源。 高压电感升压转换器为用于显示屏 能够支持高达 40V 输出电压的高压灯串,并且效率 背光和键盘功能的两个串联 LED 灯串供电(HVLED1
高达 90% 高达 90% ^和 HVLED2)。 集成电荷泵为五个低电压指示器 LED 每灌电流高达 30mA(背光和指示灯) 电流阱(LVLED1 至 LVLED5)提供偏置。 所有低压
采用 8 位可编程背光代码实现 14 位指数调光 _{中流陆均且有一种可编程图案生成器,可针对各种闪*} 电流阱均具有一种可编程图案生成器,可针对各种闪烁

宽调制 (PWM) ALS 输入 The Manager of Manager Manager State Manager Theory and The State State State State State Sta 针对内容可调亮度控制的 PWM 输入 __________________调制 (PWM) 控制输入以及一个带有 8 位内部模数转换 • 五个用于指示器 LED 的低压电流阱 器 (ADC) 的环境光传感器 (ALS) 接口,这两种功能可 用于提高效率和 VIN 工作范围的集成电荷泵 有关 机据环境光照条件自动调节电流。 PWM 和 ALS 输入 内部图案生成引擎 均可用于控制任何高电压或低电压电流阱。

LM3533 完全可由一个 I2C 兼容接口进行编程。 该器

40V) ²⁰ 引脚芯片尺寸球状引脚栅格阵列 (DSBGA) 封装, • 500kHz ^和 1MHz 可编程开关频率 其工作输入电压范围为 2.7V ^至 5.5V,工作温度范围 • 27mm² 总体解决方案尺寸 ^为 -40°C ^至 +85°C。

部件号	封装	封装尺寸(最大值)	
LM3533	DSBGA (20)	2.04mm x 1.78mm	

RGB 指示器驱动器 **Example 20 and The Connect of the Connect Connect (1)** 要了解所有可用封装,请见数据表末尾的可订购产品附录。

目录

4 修订历史记录

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision B (May 2013) to Revision C Page

Changes from Revision A (May 2013) to Revision B Page

• Changed layout of National Data Sheet to TI format ... [55](#page-54-0)

5 Pin Configuration and Functions

Pin Functions

6 Specifications

6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted) $(1)(2)(3)$

(1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

All voltages are with respect to the potential at the GND pin.

(3) If Military/Aerospace specified devices are required, contact the TI Sales Office/Distributors for availability and specifications.

(4) For detailed soldering specifications and information, refer to Texas Instruments Application Note 1112: *DSBGA Wafer Level Chip Scale Package* [\(SNVA009](http://www.ti.com/cn/lit/pdf/SNVA009)) available at www.ti.com.

6.2 ESD Ratings

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted) $⁽¹⁾$ </sup>

(1) All voltages are with respect to the potential at the GND pin.

(2) Internal thermal shutdown circuitry protects the device from permanent damage. Thermal shutdown engages at $T_J = 140^{\circ}C$ (typical) and disengages at $T = 125^{\circ}C$ (typical).

In applications where high power dissipation and/or poor package thermal resistance is present, the maximum ambient temperature may have to be derated. Maximum ambient temperature $(T_{A\text{-MAX}})$ is dependent on the maximum operating junction temperature $(T_{J\text{-MAX-OP}})$ 125°C), the maximum power dissipation of the device in the application (P_{D-MAX}) , and the junction-to ambient thermal resistance of the part/package in the application $(R_{\theta JA})$, as given by the equation: $T_{A\text{-MAX}} = T_{J\text{-MAX}} - (R_{\theta JA} \times P_{D\text{-MAX}})$.

6.4 Thermal Information

(1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report, [SPRA953.](http://www.ti.com/cn/lit/pdf/spra953)

Junction-to-ambient thermal resistance $(R_{J\theta A})$ is taken from a thermal modeling result, performed under the conditions and guidelines set forth in the JEDEC standard JESD51-7. The test board is a 4-layer FR-4 board measuring 102 mm × 76 mm × 1.6 mm with a 2 × 1 array of thermal vias. The ground plane on the board is 50 mm \times 50 mm. Thickness of copper layers are 36 μ m/18 μ m/18 μ m/36 μ m (1.5 oz/1 oz/1 oz/1.5 oz). Ambient temperature in simulation is 22°C in still air. Power dissipation is 1 W. The value of R_{0JA} of this product in the DSBGA package could fall in a range as wide as 60°C/W to 110°C/W (if not wider), depending on PCB material, layout, and environmental conditions. In applications where high maximum power dissipation exists special care must be paid to thermal dissipation issues.

6.5 Electrical Characteristics

Unless otherwise specified V_{IN} = 3.6 V; typical limits are for T_A = 25°C and minimum and maximum limits apply over the full operating ambient temperature range (−40°C ≤ T_A ≤ +85°C).

(1) LED current sink matching between HVLED1 and HVLED2 is given by taking the difference between either (IHVLED1 or IHVLED2) and the average current between the two, and dividing by the average current between the two. This simplifies to $(I_{HVLED1}$ (or IHVLED2) –

I_{HVLED(AVE)})/(I_{HVLED(AVE)}) × 100. In this test, both HVLED1 and HVLED2 are assigned to Bank A.
(2) LED current sink matching in the low-voltage current sinks (LVLED1 through LVLED5) is given as the maximum matching va between any two current sinks, where the matching between any two low voltage current sinks (X and Y) is given as $(I_{LVLEDX}$ (or I_{LVLEDY}) – $I_{AVE(X-Y)}$ / $(I_{AVE(X-Y)})$ × 100. In this test all LVLED current sinks are assigned to Bank C.

Electrical Characteristics (continued)

Unless otherwise specified V_{IN} = 3.6 V; typical limits are for T_A = 25°C and minimum and maximum limits apply over the full operating ambient temperature range (−40°C ≤ T_A ≤ +85°C).

6.6 I ²C Timing Requirements

6.7 Typical Characteristics

 $\rm{V_{IN}}$ = 3.6 V, LEDs are WLEDs part number SML-312WBCW(A), typical application circuit with L = TDK (VLF302512, 4.7 µH, 10 µH, 22 µH where specified), Schottky = On-Semi (NSR0240V2T1G), T_A = 25°C, unless otherwise specified. Efficiency is given as $V_{\text{OUT}} \times (I_{\text{HVLED1}} + I_{\text{HVLED2}})/(V_{\text{IN}} \times I_{\text{IN}})$; matching curves are given as $(\Delta I_{\text{LED MAX}}/I_{\text{LED AVE}})$.

Typical Characteristics (continued)

 V_{IN} = 3.6 V, LEDs are WLEDs part number SML-312WBCW(A), typical application circuit with L = TDK (VLF302512, 4.7 µH, 10 μ H, 22 μ H where specified), Schottky = On-Semi (NSR0240V2T1G), T_A = 25°C, unless otherwise specified. Efficiency is given as $V_{\text{OUT}} \times (I_{\text{HVLED2}} + I_{\text{HVLED2}})/(V_{\text{IN}} \times I_{\text{IN}})$; matching curves are given as $(\Delta I_{\text{LED_MAX}}/I_{\text{LED_AVE}})$.

Typical Characteristics (continued)

 V_{IN} = 3.6 V, LEDs are WLEDs part number SML-312WBCW(A), typical application circuit with L = TDK (VLF302512, 4.7 µH, 10 µH, 22 µH where specified), Schottky = On-Semi (NSR0240V2T1G), T_A = 25°C, unless otherwise specified. Efficiency is given as $V_{\text{OUT}} \times (I_{\text{HVLED1}} + I_{\text{HVLED2}})/(V_{\text{IN}} \times I_{\text{IN}})$; matching curves are given as $(\Delta I_{\text{LED_MAX}}/I_{\text{LED_AVE}})$.

Typical Characteristics (continued)

 V_{IN} = 3.6 V, LEDs are WLEDs part number SML-312WBCW(A), typical application circuit with L = TDK (VLF302512, 4.7 µH, 10 µH, 22 µH where specified), Schottky = On-Semi (NSR0240V2T1G), T_A = 25°C, unless otherwise specified. Efficiency is given as V_{OUT} × (Ι_{ΗVLED1} + Ι_{ΗVLED2})/(V_{IN} × Ι_{ΙΝ}); matching curves are given as (ΔΙ_{LED_MAX}/Ι_{LED_AVE}).

7 Detailed Description

7.1 Overview

The LM3533 provides the power for two high-voltage LED strings (up to 40 V at 30 mA each) and 5 low-voltage LEDs (up to 6 V at 30 mA each). The two high-voltage LED strings are powered from an integrated boost converter. The five low-voltage LEDs are powered from an integrated 2× charge pump.

The device is programmable over an l²C-compatible interface. Additional features include a pulse width modulation (PWM) input for content adjustable brightness control, an ambient light sensor input (ALS) for ambient light current control, and 4 programmable pattern generators for RGB and indicator blinking functions on the low-voltage LEDs.

7.2 Functional Block Diagram

7.3 Feature Description

7.3.1 Control Bank Mapping

Control of the LM3533's current sinks is not done directly, but through the programming of Control Banks. The current sinks are then assigned to the programmed Control Bank. This allows for a wide variety of current control possibilities where LEDs can be grouped and controlled via specific Control Banks (see [Figure](#page-12-1) 22).

7.3.1.1 High-Voltage Control Banks (A/B)

There are 2 high-voltage control banks (A and B). Both high-voltage current sinks can be assigned to either Control Bank A or Control Bank B. Assigning both current sinks to the same control bank allows for better LED current matching. Assigning each current sink to different control banks allows for each current sink to be programmed with a different current. The high-voltage control bank mapping is done via bits [1:0] of the Current Sink Output Configuration Register #1 (address 0x10).

7.3.1.2 Low-Voltage Control Banks (C, D, E, And F)

There are 4 low-voltage control banks (C, D, E, and F). Any low-voltage current sink (LVLED1 to LVLED5) can be assigned to any of the low-voltage control banks. Assigning every low-voltage current sink to the same control bank allows for the best matching between LEDs. Assigning each low-voltage current sink to different control banks allows for each current sink to be programmed with different current levels.

7.3.2 Pattern Generator

The LM3533 contains 4 independently programmable pattern generators for each Control Bank. Each pattern generator can have its own separate pattern: different rise and fall times, delays from turn-on, high and lowcurrent settings, and pattern high and low times.

7.3.3 Ambient Light Sensor Interface

The LM3533 contains an ambient light sensor interface (ALS). The ALS input is designed to connect to the output of either an analog output or PWM output ambient light sensor. The sensor output (or ambient light information) is digitized and processed by the LM3533. The light information is then compared against the LM3533's five user-configurable brightness zones. Each brightness zone points to a brightness zone target current. Each group of target currents forms an ALS mapper. The LM3533 has three groups of ALS Mappers where each mapper can be assigned to any of the high or low-voltage control banks (see [Figure](#page-18-0) 26).

7.3.4 PWM Input

The PWM input which can be assigned to any of the high- or low-voltage control banks. When assigned to a control bank, the programmed current in the control bank also becomes a function of the duty cycle at the PWM input.

7.3.5 HWEN Input

HWEN is the global hardware enable to the LM3533. HWEN must be pulled high to enable the device. HWEN is a high-impedance input so it cannot be left floating. When HWEN is pulled low the LM3533 is placed in shutdown, and all the registers are reset to their default state.

7.3.6 Thermal Shutdown

The LM3533 contains a thermal shutdown protection. In the event the die temperature reaches 140°C, the boost, charge pump and current sinks shut down until the die temperature drops to typically 125°C.

Feature Description (continued)

Figure 22. Functional Control Diagram

7.4 Device Functional Modes

7.4.1 High-Voltage Boost Converter

The high-voltage boost converter provides power for the two high-voltage current sinks (HVLED1 and HVLED2). The boost circuit operates using a 4.7-µH to 22-µH inductor and a 1-µF output capacitor. The selectable 500-kHz or 1-MHz switching frequency allows for the use of small external components and provides for high boostconverter efficiency. Both HVLED1 and HVLED2 feature an adaptive current regulation scheme where the feedback point (HVLED1 or HVLED2) is regulated to a minimum of 400 mV. When there are different voltage requirements in both high-voltage LED strings (string mismatch), the LM3533 regulates the feedback point of the highest voltage string to 400 mV and drop the excess voltage of the lower voltage string across the lower strings current sink.

7.4.1.1 High-Voltage Current Sinks (HVLED1 And HVLED2)

HVLED1 and HVLED2 control the current in the high-voltage LED strings. Each current sink has 5-bit full-scale current programmability and 8-bit brightness control. Either current sink can have its current set through a dedicated brightness register or be controlled via the ambient light sensor interface. Configuration of the highvoltage current sinks is done through the Control A/B Brightness Configuration Register (see [Table](#page-35-0) 8).

7.4.1.2 High-Voltage Current String Biasing

Each high-voltage current string can be powered from the LM3533's boost output (COUT) or from an external source. The Anode Connect Register bits [1:0] determine where the high-voltage current string anodes are connected. When set to 1 (default) the high-voltage current sink inputs are included in the boost feedback loop. This allows the boost converter to adjust its output voltage in order to maintain at least 400 mV at the current sink input.

When powered from alternate sources, bits [1:0] must be set to 0. This removes the particular current sink from the boost feedback loop. In these configurations the application must ensure that the headroom voltage across the high-voltage current sink is high enough to prevent the current sink from going into dropout (see the *[Typical](#page-6-0) [Characteristics](#page-6-0)* for data on the high-voltage LED current vs headroom voltage).

Setting the Anode Connect Register bits also determines how the shorted high-voltage LED String Fault flag is triggered (see *Fault [Flags/Protection](#page-28-0) Features*).

7.4.1.3 Boost Switching-Frequency Select

The LM3533's boost converter can have a 1-MHz or 500-kHz switching frequency. For a 500-kHz switching frequency the inductor must be between 10 µH and 22 µH. For the 1MHz switching frequency the inductor can be between 4.7 µH and 22 µH. The boost frequency is programmed through bit [1] of the OVP/Boost Frequency/PWM Polarity Select register.

7.4.2 Integrated Charge Pump

The LM3533 features an integrated $(2\times/1\times)$ charge pump capable of supplying up to 150 mA. The fixed 1-MHz switching frequency allows for use of tiny 1-µF ceramic flying capacitors (CP) and output capacitor (CPOUT). The charge pump can supply the power for the low-voltage LEDs connected to LVLED1 to LVLED5 and can operate in 4 different modes: disabled, automatic gain, 1x gain, or 2x gain (see [Figure](#page-13-0) 23).

Figure 23. Integrated Charge Pump

7.4.2.1 Charge Pump Disabled

With the charge pump disabled, the path from IN to CPOUT is high impedance. Additionally, with the charge pump disabled, the low-voltage current sinks can still be active, thus allowing the low-voltage LEDs to be biased from external sources (see *[Low-Voltage](#page-14-0) LED Biasing*). Disabling the charge pump also has no influence on the state of the low-voltage current sinks. For instance, if a low-voltage current string is set to have its anode connected to CPOUT, and the charge pump is disabled, the current sink continues to try to sink current.

7.4.2.2 Automatic Gain

In Automatic Gain Mode the charge pump gain transition is actively selected to maintain LED current regulation in the CPOUT-connected, low-voltage current sinks. At higher input voltages the charge pump operates in Pass Mode (1 \times gain) allowing the voltage at CPOUT to track the input voltage. As V_{IN} drops, the voltage on the lowvoltage current sink(s) also drops. Once any of the active, CPOUT-connected, low-voltage current sink input voltages reach typically 100 mV, the charge pump automatically switches to a gain of 2× thus preventing dropout (see *2× [Gain](#page-14-1)*). Once the charge pump switches over to 2× gain it remains in 2× gain, even if the current sink input voltage goes above the switch over threshold.

7.4.2.3 Automatic Gain (Flying Capacitor Detection)

In Automatic Gain Mode the LM3533 starts up and automatically detect if there is a flying capacitor (CP) connected from C+ to C−. If there is, Automatic Gain Mode operates normally. If the detection circuitry detects that there is no flying capacitor connected, the LM3533 automatically switches to 1x Gain mode.

7.4.2.4 1× Gain

In 1 \times Gain Mode the charge pump passes V_{IN} directly through to CPOUT. There is a resistive drop between IN and CPOUT in this mode (1.1Ω) which must be accounted for when determining the headroom requirement for the low-voltage current sinks. In forced 1× Gain Mode the charge pump does not switch; thus, the flying capacitor (CP) and output capacitor (CPOUT) can be omitted from the circuit.

7.4.2.5 2× Gain

In 2 \times Gain Mode the internal charge pump doubles V_{IN} and post-regulate CPOUT to typically 4.4 V. This allows for biasing LEDs whose forward voltages are greater than the input supply (V_{IN}) .

7.4.2.6 Low-Voltage Current Sinks (LVLED1 to LVLED5)

Current sinks LVLED1 to LVLED5 each provide the current for a single LED. These low-voltage sinks are configurable with different blinking patterns via the 4 internal pattern generators. Each low-voltage current sink has 8-bit brightness control and 5-bit full-scale current programmability. Additionally, each low-voltage current sink can have its current set through a dedicated brightness register, the PWM input, the ambient light sensor interface, or a combination of these. Configuration of the low-voltage current sinks is done through the lowvoltage Control Banks (C, D, E, or F). Any low-voltage current sink can be mapped to any of the low-voltage control banks.

7.4.2.7 Low-Voltage LED Biasing

Each low-voltage LED can be powered from the LM3533's charge pump output (CPOUT) or from an external source. When powered from CPOUT the anode connect bit (Anode Connect Register bits [6:2]) for that particular low-voltage current sink must be set to '1' (default). This allows for the specific low-voltage current sink to have control over the charge pumps gain control (see *[Automatic](#page-14-2) Gain* section).

When powered from alternate sources (such as VIN) the anode connect bit for the particular low-voltage current sink must be set to '0'. This removes the particular current sink from the charge pump feedback loop. In these configurations the application must ensure that the headroom voltage across the low-voltage current sink is high enough to prevent the low-voltage current sinks from going into dropout (see *Typical [Characteristics](#page-6-0)* for data on the low-voltage LED current vs headroom voltage).

The LVLEDx Anode Connect bits also determine how the Shorted low-voltage LED String fault flag is triggered (see *Fault [Flags/Protection](#page-28-0) Features*).

7.4.3 LED Current Mapping Modes

All control banks can be programmed for either exponential or linear mapping modes (see [Figure](#page-15-0) 24). These modes determine the transfer characteristic of backlight code to LED current.

7.4.3.1 Exponential Mapping

In Exponential Mapping mode the brightness code to backlight current transfer function is given by [Equation](#page-15-1) 1:

$$
I_{LED} = I_{LED_FULISCALE} \times 0.862^{\left[46.6 - \frac{\left(\frac{Co_{obs}+1}{5.5}\right)\right]}{5.5}} \times D_{PWM}
$$

where

- ILED FULLSCALE IS the full-scale LED current setting (see [Table](#page-35-1) 11)
- Code is the backlight code in the Brightness register
- D_{PWM} is the PWM input duty cycle. (1)

In Exponential Mapping mode the current ramp (either up or down) appears to the human eye as a more uniform transition then the linear ramp. This is due to the logarithmic response of the eye.

7.4.3.2 Linear Mapping

In Linear Mapping Mode the brightness code to backlight current has a linear relationship and follows [Equation](#page-15-2) 2:

$$
I_{LED} = I_{LED_FULISCALE} \times \frac{1}{255} \times Code \times D_{PWM}
$$

where

- ILED FULLSCALE IS the full-scale LED current setting
- Code is the backlight code in the Brightness register

ILED (mA)

 D_{PWM} is the PWM input duty cycle. (2)

Linear Mapping

Figure 24. LED Current Mapping Modes

7.4.4 LED Current Ramping

7.4.4.1 Start-Up/Shutdown Ramp

The startup and shutdown ramp times are independently programmable in the Start-Up/Shutdown Transition Time Register (see [Table](#page-34-0) 4). There are 8 different start-up and 8 different shutdown times. The start-up times can be programmed independently from the shutdown times, but teach Control bank is not independently programmable. For example, programming a start-up or shutdown time does not affect the already preprogrammed ramp time for each Control Bank.

The start-up ramp time is from when the Control Bank is enabled to when the LED current reaches its initial set point. The shutdown ramp time is from when the Control Bank is disabled to when the LED current reaches 0.

ISTRUMENTS

7.4.4.2 Run-Time Ramp

Current ramping from one brightness level to the next is programmed via the Run-Time Transition Time Register (see [Table](#page-34-1) 5). There are 8 different ramp-up times and 8 different ramp-down times. The ramp-up time can be programmed independently from the ramp-down time, but each Control Bank cannot be independently programmed. For example, programming a ramp-up or ramp-down time is a global setting for all Control Banks.

7.4.5 Brightness Register Current Control

For simple user-adjustable current control, the LM3533 features Brightness Register Current Control. This mode is selected via the Control Bank Brightness Configuration Registers (see [Table](#page-35-0) 8 and [Table](#page-35-2) 10). Once set for Brightness Register Current Control, the LED current is set by writing directly to the appropriate Control Bank Brightness Registers (see [Table](#page-39-0) 28). In this mode the current for a particular Control Bank becomes a function of the full-scale LED current, the 8-bit code in the respective brightness register, and the PWM input duty cycle (if PWM is enabled). The Control Bank Brightness Register contains an 8-bit code which represents the percentage of the full-scale LED current. This percentage of full-scale current is different depending on the selected mapping mode (see *LED Current [Mapping](#page-14-3) Modes*).

7.4.6 PWM Control

The LM3533 device's PWM input can be enabled for any of the Control Banks (see [Table](#page-34-2) 7). Once enabled, the LED current becomes a function of the code in the Control Bank Brightness Configuration Register and the PWM input-duty cycle.

The PWM input accepts a logic level voltage and internally filters it to an analog control voltage. This results in a linear response of duty cycle to current, where 100% duty cycle corresponds to the programmed brightness code multiplied by the Full-Scale Current setting.

7.4.6.1 PWM Input Frequency Range

The usable input frequency range for the PWM input is governed on the low end by the cutoff frequency of the internal low-pass filter (540 Hz, $Q = 0.33$) and on the high end by the propagation delays through the internal logic. For frequencies below 2 kHz the current ripple begins to become a larger portion of the DC LED current. Additionally, at lower PWM frequencies the boost output voltage ripple increases, causing a non-linear response from the PWM duty cycle to the average LED current due to the response time of the boost. For the best response of current vs. duty cycle, the PWM input frequency must be kept between 2 kHz and 100 kHz.

7.4.6.2 PWM Input Polarity

The PWM Input can be set for active low polarity, where the LED current is a function of the negative duty cycle. This is set via the OVP/Boost Frequency/PWM Polarity Register (see [Table](#page-37-0) 20).

7.4.7 ALS Current Control

The LM3533 features Ambient Light Sensor (ALS) current control which allows the LED current to be automatically set based upon the received ambient light. To implement ambient light current control the LM3533 uses a 5 brightness zone implementation with 3 sets of Zone Targets.

7.4.7.1 ALS Brightness Zones (Zone Boundaries)

The LM3533 provides for a 5 brightness zone ambient light sensor interface. This allows for the LED current in any current sink to change based upon which zone the received ambient light falls into. The brightness zones are configured via 4 ALS Zone Boundary High and 4 ALS Zone Boundary Low Registers. Each Zone Boundary register is 8 bits with a full-scale voltage of 2 V. This gives a 2 V/255 = 7.843 mV per bit. [Figure](#page-18-0) 26 shows the mapping from the ALS Brightness Zone to the target backlight current.

7.4.7.2 Zone Boundary Hysteresis

For each Zone Boundary there are two Zone Boundary Registers: a Zone Boundary High Register and a Zone Boundary Low Register (see [Table](#page-39-1) 30). The difference between the Zone Boundary High and Zone Boundary Low Registers (for a specific zone) creates the hysteresis that is required to transition between zones. This hysteresis prevents the backlight current from oscillating between zones when the ALS voltage is close to a Zone Boundary Threshold. For Zone-to-Zone transitions the increasing ALS voltage must cross the Zone Boundary High Threshold in order to get into the next higher zone. Conversely, the ALS decreasing voltage must cross below the Zone Boundary Low Threshold in order to get into the next lower zone. [Figure](#page-17-0) 25 describes this Zone Boundary Hysteresis.

Figure 25. ALS Zone Boundary + Hysteresis (1)

7.4.7.3 Zone Target Registers (ALSM1, ALSM2, ALSM3)

For each brightness zone there is a programmable brightness target which is set via the ALS Zone Target Registers (see [Table](#page-40-0) 31, [Table](#page-40-1) 32, and [Table](#page-40-2) 33). There are 3 sets of ALS Zone Target Registers (ALSM1, ALSM2, and ALSM3). The ALSM1 Zone Target Registers are dedicated to only Control Bank 1. ALSM2 and ALSM3 registers can be assigned to any of the Control Banks $(B - F)$ (see [Table](#page-35-2) 8 and Table 10). Each of the Zone Target Registers consists of an 8-bit code which is a percentage of the programmed full-scale current. This percentage of full-scale current is dependent on the selected mapping mode. [Figure](#page-18-0) 26 details the mapping of the ALS Brightness Zone to the ALSM_ Zone Target Registers.

7.4.7.4 PWM Input in ALS Mode

The PWM input can be enabled for any of the 5 Brightness Zones (see [Table](#page-34-2) 7). This makes the brightness target for the PWM enabled zone have its current a function of the PWM input duty cycle, the full-scale current setting for that particular bank, and the brightness target for that particular zone.

7.4.8 ALS Functional Blocks

[Figure](#page-18-1) 27 shows the functional block diagram of the LM3533 device ALS interface.

Figure 27. ALS Block Diagram

7.4.8.1 ALS Input

The ALS input is designed to connect to an analog or PWM output ambient light sensor. The ALS Configuration Register Bit [1] selects which type of sensor interface is used at the ALS input (see [Table](#page-38-0) 22).

7.4.8.2 Analog Output Ambient Light Sensors (ALS Gain Setting Resistors)

With ALS Cnfiguration Register bit $[1] = 0$, the ALS input is set for Analog Sensor mode. In this mode the LM3533 offers 128 programmable internal resistors at the ALS input (including a high-impedance option); see [Table](#page-38-1) 21. These resistors are designed to take the output of an analog ambient light sensor and convert it into a voltage. The value of the resistor selected is typically chosen such that the ALS input voltage is 2 V at the maximum ambient light (LUX) value. The sensed voltage at the ALS input is digitized by the LM3533's internal 8 bit ADC with a full-scale value (0xFF) corresponding to 2 V.

7.4.8.3 PWM Output Ambient Light Sensors (Internal Filtering)

With the ALS Configuration Register bit $[1] = 1$, the ALS input is set for PWM-Sensor mode. In this mode the LM3533 offers an internal level shifter and low-pass filter (ALS PWM Input mode). With this mode enabled the ALS input accepts logic level PWM signals and converts them into a 0-to-2-V analog voltage which is then filtered. This 0-to-2-V analog representation of the PWM signal is then applied to the internal 8-bit ADC, where 2 V is the full scale (code 0xFF). The internal filter has a corner frequency of 540 Hz and provides 51 dB of attenuation (355×) at a 10-kHz input frequency.

Because the internal ADC for the ambient light sensor utilizes an 8-bit ADC, the attenuation of the ALS input signal needs to be greater than $1/255$ (1 LSB = 7.843 mV) in order to realize the full 8-bit range. This forces the frequency for the PWM signal at the ALS input to be around 6 kHz or greater. For slower moving signals an external RC filter may need to be combined with the Analog Sensor Mode (see *Application and [Implementation](#page-45-0)*).

When the ALS input is set for ALS PWM Input Mode the internal ALS resistor setting is automatically set for high impedance, no matter what the setting in the ALS Select Register.

7.4.8.4 Internal 8-Bit ADC

The LM3533 digitizes the ALS voltage using an internal 8-bit ADC. The ADC is active as long as the ALS enable bit is set. Once set, the ADC begins sampling and converting the voltage at the ALS input at 7.142 ksps. The ADC output can be read back via the ADC register (address 0x37). With the ALS enable bit set, the ADC register is updated every 140 µs. [Figure](#page-19-0) 28 details the timing of the ADC.

7.4.8.5 ALS Averager

Once digitized the output of the ADC is sent into the ALS averager. The averager computes the average of the number of samples taken over the programmed average period. The ALS average times are set via bits [5:3] in the ALS Configuration Register. The output of the ALS average can be read back via the ADC Average register (address 0x38). With the ALS Enable bit set, the ADC Average register is updated after each average period (see [Figure](#page-19-0) 28). After every average period the Averager Output stores the information for which brightness zone the ALS input voltage resides in (see [Figure](#page-18-1) 27).

7.4.8.6 Initializing the ALS

On initial start-up of the ALS Interface, the Ambient Light Zone defaults to Zone 0. This allows the ALS to start off in a predictable state. The drawback is that Zone 0 is often not representative of the true ALS Brightness Zone, as the ALS input can get to its ambient light representative voltage much faster than the LED current is allowed to change. In order to avoid a multiple average time wait for the backlight current to get to its correct state, the LM3533 switches over to a fast average period (1.1 ms) during the ALS start-up. This quickly brings the ALS Brightness Zone (and the backlight current) to its correct setting (see [Figure](#page-20-0) 29).

Figure 29. ALS Start-up Sequence

7.4.8.7 ALS Algorithms

There are three ALS algorithms that can be selected independently by each ALS Mapper (ALSM1, ALSM2, and ALSM3) (see [Table](#page-38-2) 23). The ALS algorithms are: direct, up only, and down delay.

7.4.8.8 ALS Rules

For each algorithm, the ALS follows these basic rules:

- 1. For the ALS Interface to force a change in the backlight current (to a higher zone target), the averager output must have shown an increase for 3 consecutive average periods, or an increase and a remain at the new zone for 3 consecutive average periods.
- 2. For the ALS Interface to force a change in the backlight current (to a lower zone target), the averager output must have shown a decrease for 3 consecutive average periods, or a decrease and remain at the new zone for 3 consecutive average periods.
- 3. If condition 1 or 2 above is satisfied, and during the next average period the averager output changes again in the same direction as the last change, the LED current immediately changes at the beginning of the next average period.

- 4. If condition 1 or 2 above is satisfied, and the next average period shows no change in the average zone, or shows a change in the opposite direction, then the criteria in condition 1 or 2 must be satisfied again before the ALS interface can force a change in the backlight current.
- 5. The Averager Output (see [Figure](#page-18-1) 27) contains the zone that is determined from the most recent full average period.
- 6. The ALS Interface only forces a change in the backlight current at the beginning of an average period.
- 7. When the ALS forces a change in the backlight current the change is to the brightness target pointed to by the zone in the Averager Output.

7.4.8.9 Direct ALS Control

In direct ALS control the LM3533 ALS Interface can force the backlight current to either a higher zone target or a lower zone target using the rules described in *ALS [Rules](#page-20-1)*. In the example of [Figure](#page-22-0) 30, the plot shows the ALS voltage, the current average zone which is the zone determined by averaging the ALS voltage in the current average period, the Averager Output which is the zone determined from the previous full average period, and the target backlight current that is controlled by the ALS Interface. The following steps detail the Direct ALS algorithm:

- 1. When the ALS is enabled the ALS fast start-up (1.1-ms average period) quickly brings the Averager Output to the correct zone. This takes 3 fast average periods or approximately 3.3ms.
- 2. The 1st average period the ALS voltage averages to Zone 4.
- 3. The 2nd average period the ALS voltage averages to Zone 3.
- 4. The 3rd average period the ALS voltage averages to Zone 0 and the Averager Output shows a change from Zone 4 to Zone 3.
- 5. The 4th average period the ALS voltage averages to Zone 2 and the Averager Output remains at its changed state of Zone 3.
- 6. The 5th average period the ALS voltage averages to Zone 1. The Averager Output shows a change from Zone 3 to Zone 2. Because this is the 3rd average period that the Averager Output has shown a change in the decreasing direction from the initial Zone 4, the backlight current is forced to change to the current Averager Output (Zone 2's) target current.
- 7. The 6th average period the ALS voltage averages to Zone 2. The Averager Output changes from Zone 2 to Zone 1. Because this is in the same direction as the previous change, the backlight current is forced to change to the current Averager Output (Zone 1's) target current.
- 8. The 7th average period the ALS voltage averages to Zone 3. The Averager Output changes from Zone 1 to Zone 2. Because this change is in the opposite direction from the previous change, the backlight current remains at Zone 1's target.
- 9. The 8th average period the ALS voltage averages to Zone 3. The Averager Output changes from Zone 2 to Zone 3.
- 10. The 9th average period the ALS voltage averages to Zone 3. The Averager Output remains at Zone 3. Because this is the 3rd average period that the Averager Output has shown a change in the increasing direction from the initial Zone 1, the backlight current is forced to change to the current Averager Output (Zone 3's) target current.
- 11. The 10th average period the ALS voltage averages to Zone 4. The Averager Output remains at Zone 3.
- 12. The 11th average period the ALS voltage averages to Zone 4. The Averager Output changes to Zone 4.
- 13. The 12th average period the ALS voltage averages to Zone 4. The Averager Output remains at Zone 4.
- 14. The 13th average period the ALS voltage averages to Zone 4. The Averager Output remains at Zone 4. Because this is the 3rd average period that the Averager Output has shown a change in the increasing direction from the initial Zone 3, the backlight current is forced to change to the current Averager Output (Zone 4's) target current.

Figure 30. Direct ALS Control

7.4.8.10 Up-Only Control

The ALS Up-Only Control algorithm is similar to Direct ALS Control except the ALS Interface can only program the backlight current to a higher zone target. Referring to [Figure](#page-23-0) 31:

- 1. When the ALS is enabled the ALS fast startup (1.1ms average period) quickly brings the Averager Output to the correct zone. This takes 3 fast average periods or approximately 3.3 ms.
- 2. The 1st average period the ALS voltage averages to Zone 1.
- 3. The 2nd average period the ALS voltage averages to Zone 0.
- 4. The 3rd average period the ALS voltage averages to Zone 0, and the Averager Output shows a change from Zone 1 to Zone 0.
- 5. The 4th average period the ALS voltage averages to Zone 2, and the Averager Output remains at its changed state of Zone 0.
- 6. The 5th average period the ALS voltage averages to Zone 2. The Averager Output remains at Zone 0. Because the Up Only algorithm is chosen the backlight current remains at the Zone 1 target even though this is the 3rd consecutive average period that the Averager Output has shown a change since the initial Zone 1.
- 7. The 6th average period the ALS voltage averages to Zone 2. The Averager Output changes from Zone 0 to Zone 2.
- 8. The 7th average period the ALS voltage averages to Zone 3. The Averager Output remains at Zone 2.
- 9. The 8th average period the ALS voltage averages to Zone 3. The Averager Output remains at Zone 2.

Because this is the 3rd average period that the Averager Output has shown a change in the up direction, the backlight current is forced to change to the current Averager Output (Zone 2's) target current.

- 10. The 9th average period the ALS voltage averages to Zone 3. The Averager Output changes from Zone 2 to Zone 3. Because this is a change in the increasing Zone direction, and is a consecutive change following a new backlight target current transition, the backlight current is again forced to change to the current Averager Output (Zone 3's) target current.
- 11. The 10th average period the ALS voltage averages to Zone 4. The Averager Output remains at Zone 3.
- 12. The 11th average period the ALS voltage averages to Zone 4. The Averager Output changes to Zone 4.
- 13. The 12th average period the ALS voltage averages to Zone 4. The Averager Output remains at Zone 4.
- 14. The 13th average period the ALS voltage averages to Zone 4. The Averager Output remains at Zone 4. Because this is the 3rd average period that the Averager Output has shown a change in the increasing direction from the initial Zone 3, the backlight current is forced to change to the current Averager Output (Zone 4's) target current.

Figure 31. ALS Up-Only Control

7.4.8.11 Down-Delay Control

The Down-Delay algorithm uses all the same rules from *ALS [Rules](#page-20-1)*, except it provides for adding additional average period delays required for decreasing transitions of the Averager Output, before the LED current is programmed to a lower zone target current. The additional average period delays are programmed via the ALS Down Delay register. The register provides 32 settings for increasing the down delay from 3 extra (code 00000) up to 34 extra (code 11111). For example, if the down delay algorithm is enabled, and the ALS Down Delay register was programmed with 0x00 (3 extra delays), then the Averager Output would need to see 6 consecutive changes in decreasing Zones (or 6 consecutive average periods that changed and remained lower), before the backlight current was programmed to the lower zones target current. Referring to [Figure](#page-25-0) 32, assume that Down Delay is enabled, and the ALS Down Delay register is programmed with 0x02 (5 extra delays, or 8 average period total delays for downward changes in the backlight target current):

- 1. When the ALS is enabled the ALS fast startup (1.1ms average period) quickly brings the Averager Output to the correct zone. This takes 3 fast average periods or approximately 3.3 ms.
- 2. The first average period the ALS voltage averages to Zone 3.
- 3. The second average period the ALS voltage averages to Zone 2. The Averager Output remains at Zone 3.
- 4. The 3rd through 7th average period the ALS voltage averages to Zone 2, and the Averager Output stays at Zone 2.
- 5. The 8th average period the ALS voltage averages to Zone 4. The Averager Output remains at Zone 2.
- 6. The 9th and 10th average periods the ALS voltage averages to Zone 4. The Averager Output is at Zone 4. Because the Averager Output increased from Zone 2 to Zone 4 and the required Down Delay time was not met (8 average periods), the backlight current was never changed to the Zone 2's target current.
- 7. The 11th average period the ALS voltage averages to Zone 2. The Averager Output remains at Zone 4. Because this is the 3rd consecutive average period where the Averager Output has shown a change (increasing direction) since the change from Zone 2, the backlight current transitions to Zone 4's target current.
- 8. The 12th through 26th average periods the ALS voltage averages to Zone 2. The Averager Output remains at Zone 2. At the start of average period #19 the Averager Output has shown the required 8 average period delay from the initial change from Zone 4 to Zone 2. As a result the backlight current is programmed to Zone 2's target current.

FXAS NSTRUMENTS

Device Functional Modes (continued)

Figure 32. ALS Down-Delay Control

7.4.9 Pattern Generator

The LM3533 contains 4 programmable pattern generators (one for each low-voltage control bank). Each pattern generator has the ability to drive a unique programmable pattern. Each pattern generator has its own set of registers available for pattern programming. The programmable patterns are : delay time, rise time, fall time, high period, low period, high current and low current (see [Figure](#page-25-1) 33).

Figure 33. Pattern Generator Timing

7.4.9.1 Delay Time

The Delay time (t_{DELAY}) is the delay from when the pattern is enabled to when the LED current begins ramping up in the control bank's assigned current source(s). The pattern starts when bit [3] of the respective Control Bank Brightness Configuration Register is written high. There is one t_{DELAY} register for each pattern generator (4 total). The selectable times are programmed with the lower 6 bits of the t_{DELAY} registers. The times are split into 2 groups where codes 0x00 to 0x3C are short durations from 16.384 ms (code 0x00) up to 999.424 ms (code 0x3C) or 16.384 ms/bit. The higher codes (0x3D to 0x7F) select t_{DELAY} from 1130.496 ms up to 9781.248 ms, or 131.072 ms/bit (see [Table](#page-41-0) 35).

7.4.9.2 Rise Time

The LED current rise time (t_{RISE}) is the time the LED current takes to move from the low-current brightness level (I_{LOW}) to the high-current brightness level (I_{HIGH}) . The rise time of the LED current (t_{RISE}) is set via the Pattern Generator Rise Time Registers. Each Pattern Generator has its own rise-time register. There are 8 available rise-time settings (see [Table](#page-43-0) 42).

7.4.9.3 Fall Time

The LED current fall time (t_{FALL}) is the time the LED current takes to move from the high-current brightness level (I_{HIGH}) to the low-current brightness level (I_{LOW}) . The fall time of the LED current (t_{FALL}) is set via the Pattern Generator Fall Time Registers. Each Pattern Generator has its own fall-time register. There are 8 available falltime settings (see [Table](#page-43-1) 43).

7.4.9.4 High Period

The LED current high period (t_{HIGH}) is the duration that the LED pattern spends at the high LED current set point (t_{HIGH}) . The t_{HIGH} times are programmed via the Pattern Generator t_{HIGH} Registers. The programmable times are broken into 2 groups. The first set (from code 0x00 to 0x3C) increases the t_{HIGH} time in steps of 16.384 ms. The second set (from code 0x3D to 0x7F) increases the t_{HIGH} time in steps of 131.072 ms (see [Table](#page-42-0) 39).

7.4.9.5 Low Period

The LED current low period (t_{LOW}) is the duration that the LED current spends at the low LED current set point (I_{LOW}). The t_{LOW} times are programmed via one of the Pattern Generator t_{LOW} Registers. There are 256 t_{LOW} settings and are broken into 3 groups of linearly increasing times. The first set (from code 0x00 to 0x3C) increases the t_{LOW} time in steps of 16.384ms. The second set (from code 0x3D to 0x7F) increases the t_{LOW} time in steps of 131.072 ms. The third set (from code 0x80 to 0xFF) increases the t_{LOW} time in steps of 524.288 ms (see [Table](#page-41-1) 37).

7.4.9.6 Low-Level Brightness

The LED current low brightness level (I_{LOW}) is the LED current set point that the pattern rests at during the t_{LOW} period. This level is set via the Pattern Generator Low Level Brightness Register(s). The brightness level has 8 bits of programmability. I_{low} is a function of the Control Banks full-scale Current setting, the code in the Pattern Generator Low-Level Brightness Register, the Mapping Mode selected, and the PWM input duty cycle (if PWM is enabled).

For exponential mapping I_{LOW} is:

$$
I_{LOW} = I_{LED_FULISCALE} \times 0.85^{\left[40 \cdot \left(\frac{\text{BREGL_X+1}}{6.4}\right)\right]} \times D_{PWM}
$$

For linear mapping I_{LOW} is:

$$
I_{LOW} = I_{LED_FULISCALE} \times \frac{1}{255} \times BREGL_X \times D_{PWM}
$$

(4)

(3)

BREGL_X is the Pattern Generator Low-Level Brightness Register setting for the specific Control Bank (see [Table](#page-42-1) 40).

(5)

(6)

Device Functional Modes (continued)

7.4.9.7 High-Level Brightness

The LED current high brightness level (I_{HIGH}) is the LED current set point that the pattern rests at during the t_{HIGH} period. This high-current level is set via the Control Banks Brightness Register (BREGCH to BREGFH). The brightness level has 8 bits of programmability. I_{HIGH} is a function of the Control Banks Full-Scale Current setting, the code in the Control Banks Brightness Register, the Mapping Mode selected, and the PWM input duty cycle (if PWM is enabled).

For exponential mapping I_{HIGH} is:

$$
I_{LED} = I_{LED_ FULISCALE} \times 0.862^{\left[46.6\cdot\left(\frac{Code+1}{5.5}\right)\right]} \times D_{PWM}
$$

For linear mapping $I_{H \cap G}$ is:

$$
I_{\text{HIGH}} = I_{\text{LED_FULISCALE}} \times \frac{1}{255} \times \text{BREGH_X} \times D_{\text{PWM}}
$$

BREGH_X is the Control Banks Brightness Register setting for the specific Control Bank (see [Table](#page-39-0) 28).

7.4.9.8 ALS Controlled Pattern Current

The current levels (I_{HIGH} and I_{LOW}) of the programmable pattern can also be influenced by the ALS input. All the same ALS algorithms apply to the pattern generator current levels (Direct, Up Only, and Down Delay). The difference, however, for the ALS Controlled Pattern Current is that the pattern current is not changed to zonedefined brightness targets, but is changed by a scaled factor of the existing I_{HIGH} and I_{LOW} levels. These scaled factors are programmable in the ALS Pattern Scaler Registers (see [Table](#page-37-1) 17, [Table](#page-37-2) 18, and [Table](#page-37-3) 19). Each defined brightness zone has a 4-bit (16-level) scale factor, which takes the programmed pattern current code and multiplies it by the programmed scale factor. This produce a new I_{HIGH} and I_{LOW} current level ranging from 1/16 \times BREGH and 1/16 x BREGL up to 16/16 x BREGH and 16/16 x BREGL for each ALS zone (see [Figure](#page-27-0) 34). There is only one set of scale factors for all the pattern generators.

Figure 34. ALS Controlled Pattern Current Scaling

For low-voltage control banks that do not have their pattern generator enabled, ALS current control is done via the ALS Mappers. Once a pattern generator is enabled, that particular Control Bank then uses the pattern scalers for ALS Current Control.

7.4.9.9 Interrupt Output Mode

When INT Mode is enabled (ALS Zone Information Register Bit $[0] = 1$), INT pin is configured as an interrupt output. INT is an open-drain output with an active pulldown of typically 66 Ω. In INT Mode the INT output pulls low if the ALS interface is enabled, and the ALS input has changed zones. Reading back the ALS Zone Information while in this mode clears the INT output and reset it to its open-drain state.

7.4.10 Fault Flags/Protection Features

The LM3533 contains both an LED open and LED short fault detection. These fault detections are designed to be used in production level testing and not normal operation. For the fault flags to operate, they must be enabled via the LED Fault Enable Register (see [Table](#page-44-0) 47).

7.4.10.1 Open LED String (HVLED)

An open LED string is detected when the voltage at the input to any active high-voltage current sink has fallen below 200 mV, and the boost output voltage has hit the OVP threshold. This test assumes that the HVLED string that is being detected for an open is connected to the LM3533 boost output (COUT+) (see [Table](#page-36-0) 13). For an HVLED string not connected to the LM3533 boost output voltage, but connected to another voltage source, the boost output will not trigger the OVP flag. In this case an open LED string is not detected.

The procedure for detecting an open fault in the HVLED current sinks (provided they are connected to the boost output voltage) is:

- Apply power to the LM3533
- Enable Open Fault (Register 0xB2, bit [0] = 1)
- Configure HVLED1 and HVLED2 for LED string anode connected to COUT (Register 0x25, bits[1:0] = $(1,1)$
- Set Bank A full-scale current to 20.2 mA (Register $0x1F = 0x13$)
- Set Bank A brightness to max (Register $0x40 = 0xFF$)
- Set the startup ramp times to the fastest setting (Register $0x12 = 0x00$)
- Assign HVLED1 and HVLED2 to Bank A (Register 0x10, Bits $[1:0] = (0, 0)$
- Enable Bank A (Register $0x27$ Bit $[0] = 1$
- Wait 4ms
- Read back bits[1:0] of register 0xB0. Bit $[0] = 1$ (HVLED1 open). Bit $[1] = 1$ (HVLED2 open)
- Disable all banks (Register $0x27 = 0x00$)

7.4.10.2 Shorted LED String (HVLED)

The LM3533 features an LED short fault flag indicating one or more of the HVLED strings have experienced a short. The method for detecting a shorted HVLED strings is if the current sink is enabled and the string voltage (V_{OUT} – $V_{HVLED1/2}$) falls to below (V_{IN} – 1 V). This test must be performed on one HVLED string at a time. Performing the test with both current sinks enabled can result in a faulty reading if one of the strings is shorted and the other is not.

The procedure for detecting a short in an HVLED string is:

- Apply power to the LM3533
- Enable Short Fault (Register 0xB2, bit $[1] = 1$)
- Enable Feedback on the HVLED Current Sinks (Register $0x25 = 0xFF$)
- Set Bank A full-scale current to 20.2 mA (Register $0x1F = 0x13$)
- Set Bank A brightness to max (Register $0x40 = 0xFF$)
- Set the startup ramp times to the fastest setting (Register $0x12 = 0x00$)
- Assign HVLED1 to Bank A (Register $0x10$, Bits $[1:0] = (1, 0)$
- Enable Bank A (Register 0x27 Bit[0] = 1
- Wait 4 ms

- Read back bits[0] of register $0xB1$. $1 = HVLED1$ open
- Disable all banks (Register 0x27 = 0x00)
- Repeat the procedure for the HVLED2 string

7.4.10.3 Open LED (LVLED)

The LM3533 features an open LED fault flag indicating one or more of the active LVLED strings are open. An open in an LVLED string is flagged if the voltage at the input to any active low-voltage current sink goes below 110 mV.

Because the open LED detect is flagged when any active current sink input falls below 110 mV, certain configurations can result in falsely triggering an open. These include:

- 1. LED anode tied to CPOUT, charge pump in 1× gain, and VIN drops low enough to bring any active LVLED current sink below 110 mV.
- 2. LED anode not tied to CPOUT and VLED_ANODE goes low enough to bring any active LVLED current sink below 110 mV.

The following list describes a test procedure that can be used in detecting an open in the LVLED strings:

- Apply power to the LM3533
- Enable Open Fault (Register 0xB2, bit [0] = 1)
- Configure all LVLED strings for Anode connected to CPOUT (register $0x25$ bits[6:2] = 1)
- Force the Charge Pump into 2x gain (Register 0x26 Bits[2:1] = 11). Ensure that CPOUT and CP are in the circuit and that $(V_{CPOUT}$ is > $VF_{LVLED} + V_{HR LV})$
- Set Bank C full-scale Current to 20.2 mA (Register 0x21 = 0x13)
- Set Bank C brightness to max (Register 0x42 = 0xFF)
- Set the startup ramp times to the fastest setting (Register $0x12 = 0x00$)
- Assign LVLED1 LVLED5 to Bank C (Register $0x11 = 0x00$, Register $0x10 = 0x00$)
- Enable Bank C (Register 0x27 Bit[2] = 1
- Wait 4ms
- Read back bits[6:2] of register 0xB0. 1 indicates an open and a 0 indicates normal operation (see [Table](#page-43-2) 45).
- Disable all banks (Register 0x27 = 0x00)

7.4.10.4 Shorted LED (LVLED)

The LM3533 features an LED short fault flag indicating when any active low-voltage LED is shorted (anode to cathode). A short in an LVLED is determined when the LED voltage ($V_{CPOUT} - V_{HR}$) falls below 1 V.

A procedure for determining a short in an LVLED string is:

- Apply Power
- Enable Short Fault (Register 0xB2, bit $[1] = 1$)
- Enable Feedback on the LVLED Current Sinks (Register $0x25 = 0xFF$)
- Set Bank C full-scale current to 20.2 mA (Register 0x21 = 0x13)
- Set Bank C brightness to max (Register 0x42 = 0xFF)
- Set the startup ramp times to the fastest setting (Register $0x12 = 0x00$)
- Assign LVLED1 to LVLED5 to Bank C (Register $0x11 = 0x00$, Register $0x10 = 0x00$)
- Set Charge Pump to $1 \times$ gain (Register 0x26 = 0x40)
- Enable Bank C (Register 0x27 Bit[2] = 1
- Wait 4ms
- Read bits[6:2] from register 0xB1. A 1 indicates short, and a 0 indicates normal (see [Table](#page-44-1) 46).
- Disable all banks (Register 0x27 = 0x00)

7.4.10.5 Overvoltage Protection (Inductive Boost)

The overvoltage protection threshold (OVP) on the LM3533 has 4 different programmable options (16 V, 24 V, 32 V, and 40 V). The OVP protects the device and associated circuitry from high voltages in the event the highvoltage LED string becomes open. During normal operation, the LM3533 inductive boost converter boosts the output up so as to maintain at least 400 mV at the active, high-voltage (C_{OUT} connected) current sink inputs. When a high-voltage LED string becomes open, the feedback mechanism is broken, and the boost converter overboosts the output. When the output voltage reaches the OVP threshold the boost converter stops switching, thus allowing the output node to discharge. When the output discharges to V_{OVP} – 1 V the boost converter begins switching again. The OVP sense is at the OVP pin, so this pin must be connected directly to the inductive boost output capacitor's positive terminal.

For high-voltage current sinks that have the Anode Connect Register setting such that the high-voltage current sinks anodes are not connected to COUT (feedback is disabled), the over-voltage sense mechanism is not in place to protect the input to the high-voltage current sink. In this situation the application must ensure that the voltage at HVLED1 or HVLED2 doesn't exceed 40 V.

The default setting for OVP is set at 16 V. For applications that require higher than 16 V at the boost output, the OVP threshold must be programmed to a higher level after powerup.

7.4.10.6 Current Limit (Inductive Boost)

The NMOS switch current limit for the LM3533 inductive boost is set at 1 A. When the current through the LM3533 NFET switch hits this overcurrent protection threshold (OCP), the device turns the NFET off and the inductor's energy is discharged into the output capacitor. Switching is then resumed at the next cycle. The current limit protection circuitry can operate continuously each switching cycle. The result is that during highoutput power conditions the device can continuously run in current limit. Under these conditions the LM3533's inductive boost converter stops regulating the headroom voltage across the high-voltage current sinks. This results in a drop in the LED current.

7.4.10.7 Current Limit (Charge Pump)

The LM3533 charge pump's output current limit is set high enough so that the device supports 29.8 mA (maximim full-scale current) in all LVLED current sinks. This would typically be (29.5 mA \times 5 = 149 mA. For 1 \times gain the output current limit is typically 350 mA (V_{IN} = 3.6 V). For 2x gain the current limit is typically 240 mA (output referred), with a typical limit on the input current of 480 mA. The *Typical [Characteristics](#page-6-0)* detail the charge pump current limit vs V_{IN} at both 1x and 2x gain settings (see *Typical [Characteristics](#page-6-0)*).

7.5 Programming

7.5.1 I ²C-Compatible Interface

7.5.1.1 Start and Stop Conditions

The LM3533 is controlled via an I²C-compatible interface. START and STOP conditions classify the beginning and the end of the I²C session. A START condition is defined as SDA transitioning from HIGH to LOW while SCL is HIGH. A STOP condition is defined as SDA transitioning from LOW to HIGH while SCL is HIGH. The I²C master always generates START and STOP conditions. The ¹²C bus is considered busy after a START condition and free after a STOP condition. During data transmission the I²C master can generate repeated START conditions. A START and a repeated START condition are equivalent function-wise. The data on SDA must be stable during the HIGH period of the clock signal (SCL). In other words, the state of SDA can only be changed when SCL is LOW.

Programming (continued)

Figure 35. Start and Stop Sequences

7.5.1.2 I ²C-Compatible Address

The chip address for the LM3533 is 0110110 (36h) for the -40 device and 0111000 (38h) for the -40A device. After the START condition, the I²C master sends the 7-bit chip address followed by an eighth read or write bit (R/W). R/W= 0 indicates a WRITE and R/W = 1 indicates a READ. The second byte following the chip address selects the register address to which the data is written. The third byte contains the data for the selected register.

7.5.1.3 Transferring Data

Every byte on the SDA line must be eight bits long, with the most significant bit (MSB) transferred first. Each byte of data must be followed by an acknowledge bit (ACK). The acknowledge related clock pulse (9th clock pulse) is generated by the master. The master releases SDA (HIGH) during the 9th clock pulse. The LM3533 pulls down SDA during the 9th clock pulse signifying an acknowledge. An acknowledge is generated after each byte has been received.

[Table](#page-31-1) 1 lists the available registers within the LM3533.

7.6 Register Maps

7.6.1 LM3533 Register Descriptions

Name	Address	Power On Reset
Current Sink Output Configuration 1	0x10	0x92
Current Sink Output Configuration 2	0x11	0x0F
Start Up/Shut Down Ramp Rates	0x12	0x00
Run Time Ramp Rates	0x13	0x00
Control Bank A PWM Configuration	0x14	0x38
Control Bank B PWM Configuration	0x15	0x38
Control Bank C PWM Configuration	0x16	0x38
Control Bank D PWM Configuration	0x17	0x38
Control Bank E PWM Configuration	0x18	0x38
Control Bank F PWM Configuration	0x19	0x38
Control Bank A/B Brightness Configuration	0x1A	0x00
Control Bank C Brightness Configuration	0x1B	0x00
Control Bank D Brightness Configuration	0x1C	0x00
Control Bank E Brightness Configuration	0x1D	0x00
Control Bank F Brightness Configuration	0x1E	0x00
Control Bank A Full-Scale Current	0x1F	0x13
Control Bank B Full-Scale Current	0x20	0x13
Control Bank C Full-Scale Current	0x21	0x13
Control Bank D Full-Scale Current	0x22	0x13
Control Bank E Full-Scale Current	0x23	0x13

Table 1. LM3533 Register Definitions

Register Maps (continued)

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Register Maps (continued)

Table 3. Output Configuration Register 2 (Address 0x11)

Table 4. LED Current Start-Up/Shutdown Transition Time Register (Address 0x12)

Table 5. LED Current Run-Time Transition Time Register (Address 0x13)

Table 6. Control Bank PWM Configuration Registers (Addresses 0x14 to 0x19)

Table 7. Control Bank PWM Configuration Register Bit Settings

Table 8. Control Bank A/B Brightness Configuration Register (Address 0x1A)

Table 9. Low-Voltage Control Bank Brightness Configuration Registers (Addresses 0x1B, 0x1C, 0x1D, 0x1E)

Table 10. Low-Voltage Control Bank Brightness Configuration Register Bit Settings

Table 11. Control Bank Full-Scale Current Registers (Addresses 0x1F, 0x20, 0x21, 0x22, 0x23, 0x24)

Table 12. Control Bank Full-Scale Current Register Bit Settings

Table 13. Anode Connect Register (Address 0x25)

Table 14. Charge Pump Control Register (Address 0x26)

Table 15. Control Bank Enable Register (Address 0x27)

Table 16. Pattern Generator Enable/ALS Scaling Control (Address 0x28)

Table 16. Pattern Generator Enable/ALS Scaling Control (Address 0x28) (continued)

Note: If a low-voltage control bank is set to receive its brightness information from either ALSM2 or ALSM3, and then a pattern generator is enabled for that Control Bank, the Control Bank ignores the ALSM2 or ALSM3 zone target information. This prevents conflicts from ALSM2/ALSM3 zone targets and ALS controlled pattern currents.

Table 17. ALS Zone Pattern Scaler 1 (Address 0x29)

Table 18. ALS Zone Pattern Scaler 2 (Address 0x2A)

Table 19. ALS Zone Pattern Scaler 3 (Address 0x2B)

Table 20. OVP/Boost Frequency/PWM Polarity Select (Address 0x2C)

Table 21. R_ALS Select Register (Address 0x30)

The selectable codes are available which give a linear step in currents of 10 µA per code based upon 2V/R_ALS. This gives a code to resistance relationship of:

$$
R_{ALS} = \frac{2V}{10 \mu A \times Code(D)}
$$

(8)

Table 22. ALS Configuration Register (Address 0x31)

Table 23. ALS Algorithm Select Register (Address 0x32)

Table 24. ALS Down Delay Control Register (Address 0x33)

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Table 26. Read-Back ADC Register (Address 0x37)

This register contains the ADC data from the internal 8-bit ADC. This is a read-only register. When the ALS Interface is enabled this register is updated with the digitized ALS information every 140µs.

This register is updated after each average period.

Table 28. Brightness Registers (Addresses 0x40, 0x41, 0x42, 0x43, 0x44, 0x45)

Table 29. Brightness Registers Bit Description

Brightness Code Bits[7:0}

When the Mapping Mode is set for exponential mapping (Control Bank_Brightness Configuration Register Bit [2] = 0), the current approximates the equation:

$$
I_{LED} = I_{LED_FULLSCALE} \times 0.85^{40 \cdot \left(\frac{Coode + 1}{6.4}\right)}
$$

When the Mapping Mode is set for linear mapping (Control Bank_Brightness Configuration Register Bit [2] = 1), the current approximates the equation:

 $I_{LED} = I_{LED_FULLSCALE} \times \frac{1}{255} \times Code$

(10)

(9)

Table 30. ALS Zone Boundary High And Low Registers (Addresses 0x50 - 0x57)

Table 30. ALS Zone Boundary High And Low Registers (Addresses 0x50 - 0x57) (continued)

Note: Each Zone Boundary register is 8 bits with a maximum voltage of 2 V. This gives a step size for each Zone Boundary Register bit of:

ZoneBoundaryLSB = $\frac{2V}{255}$ = 7.8 mV

(11)

Table 31. ALSM1 Zone Target Registers (Addresses 0x60 to 0x64)

Table 32. ALSM2 Zone Target Registers (Addresses 0x65 to 0x69)

Table 33. ALSM3 Zone Target Registers (Addresses 0x6A to 0x6E)

When the Mapping Mode is set for exponential mapping (Control Bank_Brightness Configuration Register Bit [2] $= 0$), the current approximates [Equation](#page-40-3) 12:

$$
I_{LED} = I_{LED_FULISCALE} \times 0.85^{\left[40 \cdot \frac{\left(\frac{Code + 1}{64}\right)\right]}
$$

(12)

When the Mapping Mode is set for linear mapping (Control Bank_Brightness Configuration Register Bit [2] = 1), the current approximates [Equation](#page-40-4) 13:

$$
I_{LED} = I_{LED_FULLSCALE} \times \frac{1}{255} \times Code
$$

(13)

7.6.1.1 Pattern Generator Registers

Figure 36. Pattern Generator Timing

Table 34. Pattern Generator Delay Registers (Addresses 0x70, 0x80, 0x90, 0xA0)

Table 35. Pattern Generator Delay Register Bit Description

Table 36. Pattern Generator Low-Time Registers (Addresses 0x71, 0x81, 0x91, 0xA1)

Table 37. Pattern Generator Low-Time Register Bit Description

Table 38. Pattern Generator High-Time Registers (Addresses 0x72, 0x82, 0x92, 0xA2)

Table 39. Pattern Generator High-Time Register Bit Description

Table 40. Pattern Generator Low-Level Brightness Registers (Addresses 0x73, 0x83, 0x93, 0xA3)

For Exponential Mapping Mode the low-level current becomes:

$$
I_{LED_LOW_LEVEL} = I_{LED_FULISCALE} \times 0.85 \left[40 \cdot \frac{\left(\text{Code} + 1 \right)}{6.4} \right]
$$

For Linear Mapping Mode the low-level current becomes:

$$
I_{LED_LOW_LEVEL} = I_{LED_FULISCALE} \times \frac{1}{255} \times Code
$$

(15)

 (14)

Note: The Pattern Generator high level brightness setting is set through the Control Bank Brightness Registers (see [Table](#page-39-0) 28).

Table 41. Pattern Generator Rise-Time Registers (Addresses 0x74, 0x84, 0x94, 0xA4)

Table 42. Pattern Generator Rise-Time Register Bit Settings

Table 43. Pattern Generator Fall-Time Registers (Addresses 0x75, 0x85, 0x95, 0xA5)

Table 44. Pattern Generator Fall-Time Register Bit Settings

Table 45. Led String Open Fault Readback Register (Address 0xB0)

Table 47. LED Fault Enable (Address 0xB2)

8 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

The LM3533 is a dual-string (up to 40 V at up to 30 mA) backlight driver with five integrated low voltage indicator current sinks. The current through any LED can be controlled by the I²C bus, the PWM input, or via an external ambient light sensor. Any low voltage current sink can be made to blink via a programmable pattern. The programmable pattern can have variable high pulse time, low pulse time, delay from start, high time current, low time current, and ramp rates. The device operates from a typical V_{IN} from 2.7 V to 5.5 V, and an ambient temperature range of -40°C to +85°C.

8.2 Typical Application

Figure 37. LM3533 Typical Application

Typical Application (continued)

8.2.1 Design Requirements

For typical lighting power-source applications, use the parameters listed in [Table](#page-46-0) 48.

8.2.2 Detailed Design Procedure

Table 49. Application Circuit Component List

8.2.2.1 Boost Converter Maximum Output Power (Boost)

The LM3533 maximum output power is governed by two factors: the peak current limit (I_{CL} = 880 mA minimum), and the maximum output voltage (V_{OVP}). When the application causes either of these limits to be reached, it is possible that the proper current regulation and matching between LED current strings may not be met.

8.2.2.2 Peak Current Limited

In the case of a peak current limited situation, when the peak of the inductor current hits the LM3533 current limit, the NFET switch turns off for the remainder of the switching period. If this happens each switching cycle the LM3533 regulates the peak of the inductor current instead of the headroom across the current sinks. This can result in the dropout of the boost output connected current sinks, and the LED current dropping below its programmed level.

The peak current in a boost converter is dependent on the value of the inductor, total LED current in the boost (I_{OUT}), the boost output voltage (V_{OUT}) (which is the highest voltage LED string + 0.4 V regulated headroom voltage), the input voltage (V_{IN}) , the switching frequency, and the efficiency (Output Power/Input Power). Additionally, the peak current is different depending on whether the inductor current is continuous during the entire switching period (CCM), or discontinuous (DCM) where it goes to 0 before the switching period ends. For Continuous Conduction Mode the peak inductor current is given by:

$$
IPEAK = \frac{IOUT \times VOUT}{VIN \times efficiency} + \left[\frac{VIN}{2 \times f_{SW} \times L} \times \left(1 - \frac{VIN \times efficiency}{VOUT} \right) \right]
$$
(16)

For DCM the peak inductor current is given by:

$$
I_{PEAK} = \sqrt{\frac{2 \times I_{OUT}}{f_{SW} \times L \times efficiency}} \times (V_{OUT} - V_{IN} \times efficiency)
$$
\n(17)

 $V_{\text{PEAK}} = \sqrt{\frac{\sum_{i} N_{\text{OOH}}}{}\sum_{i} N_{\text{OOH}}} \times (V_{\text{OUT}} - V_{\text{IN}} \times \text{efficiency})$

For the inductor current ripple is less than the

is operating in CCM. If ΔI_L is greater than I_{IN}
 $V_{\text{ON}} \times V_{\text{OUT}} \times V_{\text{OUT}} \times \frac{V_{\text{IN}}}{f_{$ To determine which mode the circuit is operating in (CCM or DCM) it is necessary to perform a calculation to test whether the inductor current ripple is less than the anticipated input current (l_{IN}). If Δl_L is less than l_{IN} then the device is operating in CCM. If $ΔI_L$ is greater than I_{IN} then the device is operating in DCM.

$$
\frac{I_{\text{OUT}} \times V_{\text{OUT}}}{V_{\text{IN}} \times \text{efficiency}} > \frac{V_{\text{IN}}}{f_{\text{SW}} \times L} \times \left(1 - \frac{V_{\text{IN}} \times \text{efficiency}}{V_{\text{OUT}}}\right)
$$
\n(18)

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Typically at currents high enough to reach the LM3533 device's peak current limit, the device is operating in CCM. When choosing the switching frequency and the inductor value, [Equation](#page-46-1) 16 and [Equation](#page-46-2) 17 must be used to ensure that I_{PEAK} stays below I_{CL_MIN} (see *Electrical [Characteristics](#page-4-0)*).

8.2.2.3 Output Voltage Limited

In the case of a output voltage limited situation, when the boost output voltage hits the LM3533 OVP threshold, the NFET turns off and stays off until the output voltage falls below the hysteresis level (typically 1 V below the OVP threshold). This results in the boost converter regulating the output voltage to the programmed OVP threshold (16 V, 24 V, 32 V, or 40 V), causing the current sinks to go into dropout. The default OVP threshold is set at 16 V. For LED strings higher than typically 4 series LEDs, the OVP has to be programmed higher after power-up or after a HWEN reset.

8.2.2.4 Maximum Output Power (Charge Pump)

The maximum output power available from the LM3533 charge pump is determined by the maximum output voltage available from the charge pump. In 1× gain the charge pump operates in Pass Mode so that the voltage at CPOUT tracks V_{IN} (less the drop across the charge pumps pass switch). In this case the maximum output power is given as:

where

- R_{CP} is the resistance from IN to CPOUT
- $I_{\text{LVLED TOTAL}}$ is the maximum programmed current in the LVLED strings. (19)

 $P_{\text{OUT_MAX}} = I_{\text{LVLED_TOTAL}} \times (V_{\text{IN}} - I_{\text{LVLED_TOTAL}} \times R_{\text{CP}})$
 P_{C} is the resistance from IN to CPOUT
 $I_{\text{LVLED_TOTAL}}$ is the maximum programme

the voltage at CPOUT ($V_{\text{CPOUT_2X}}$) is
 $P_{\text{OUT_MAX}} = I_{\text{LVLED_TOTAL}} \times V_{\text{CPOUT_2X}}$ In 2x gain the voltage at CPOUT (V_{CPOUT_2X}) is regulated to typically 4.4 V. In this case the maximum output power is given by:

(20)

[Equation](#page-47-0) 19 and [Equation](#page-47-1) 20 both assume there is sufficient headroom at the top side of the low-voltage current sinks to ensure the LED current remains in regulation (V_{HRLV}) in the *Electrical [Characteristics](#page-4-0)*.

8.2.3 Application Curves

 V_{IN} = 3.6 V, LEDs are WLEDs part number SML-312WBCW(A), typical application circuit with L = TDK (VLF302512, 4.7 µH, 10 µH, 22 µH where specified), Schottky = On-Semi (NSR0240V2T1G), T_A = 25°C, unless otherwise specified. Efficiency is given as $V_{\text{OUT}} \times (I_{\text{HVLED1}} + I_{\text{HVLED2}})/(V_{\text{IN}} \times I_{\text{IN}})$; matching curves are given as $(\Delta I_{\text{LED_MAX}}/I_{\text{LED_AVE}})$.

 V_{IN} = 3.6 V, LEDs are WLEDs part number SML-312WBCW(A), typical application circuit with L = TDK (VLF302512, 4.7 µH, 10 µH, 22 µH where specified), Schottky = On-Semi (NSR0240V2T1G), T_A = 25°C, unless otherwise specified. Efficiency is given as $V_{\text{OUT}} \times (I_{\text{HVLED1}} + I_{\text{HVLED2}})/(V_{\text{IN}} \times I_{\text{IN}})$; matching curves are given as $(\Delta I_{\text{LED_MAX}}/I_{\text{LED-AVE}})$.

 V_{IN} = 3.6 V, LEDs are WLEDs part number SML-312WBCW(A), typical application circuit with L = TDK (VLF302512, 4.7 µH, 10 μ H, 22 μ H where specified), Schottky = On-Semi (NSR0240V2T1G), T_A = 25°C, unless otherwise specified. Efficiency is given as V_{OUT} x (I_{HVLED1} + I_{HVLED2})/(V_{IN} x I_{IN}); matching curves are given as (ΔI_{LED MAX}/I_{LED AVE}).

9 Power Supply Recommendations

The LM3532 is designed to operate from an input supply range of 2.7 V to 5.5 V. This input supply must be wellregulated and provide the peak current required by the LED configuration and inductor selected.

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10 Layout

10.1 Layout Guidelines

10.1.1 Boost

The LM3533 inductive boost converter sees a high switched voltage (up to 40 V) at the SW pin, and a step current (up to 1 A) through the Schottky diode and output capacitor each switching cycle. The high switching voltage can create interference into nearby nodes due to electric field coupling $(I = CdV/dt)$. The large step current through the diode and the output capacitor can cause a large voltage spike at the SW pin and the OVP pin due to parasitic inductance in the step current conducting path $(V = \text{Ldi/dt})$. Board layout guidelines are geared towards minimizing this electric field coupling and conducted noise. [Figure](#page-51-2) 53 highlights these two noisegenerating components.

Figure 53. LM3533 Inductive Boost Converter Showing Pulsed Voltage at SW (High Dv/Dt) and Current Through Schottky and C_{OUT}(High Di/Dt)

The following list details the main (layout sensitive) areas of the LM3533 inductive boost converter in order of decreasing importance:

- 1. Output Capacitor:
	- Schottky Cathode to COUT+
	- COUT− to GND

Layout Guidelines (continued)

- 2. Schottky Diode:
	- SW Pin to Schottky Anode
	- Schottky Cathode to COUT+
- 3. Inductor:
	- SW Node PCB capacitance to other traces
- 4. Input Capacitor:
	- CIN+ to IN pin

10.1.1.1 Boost Output Capacitor Selection and Placement

The LM3533 inductive boost converter requires a 1-µF output capacitor. The voltage rating of the capacitor depends on the selected OVP setting. For the 16-V setting a 16-V capacitor must be used. For the 24-V setting a 25-V capacitor must be used. For the 32-V setting, a 35-V capacitor must be used. For the 40-V setting a 50-V capacitor must be used. Pay careful attention to the capacitor's tolerance and DC bias response. For proper operation the degradation in capacitance due to tolerance, DC bias, and temperature, must stay above 0.4 µF. This might require placing two devices in parallel in order to maintain the required output capacitance over the device operating range, and series LED configuration.

Because the output capacitor is in the path of the inductor current discharge path, a high-current step from 0 to I_{PEAK} is seen each time the switch turns off and the Schottky diode turns on. Any inductance along this series path from the cathode of the diode through C_{OUT} and back into the LM3533 GND pin contributes to voltage spikes ($V_{\text{SPIKF}} = LP_x$ dl/dt) at SW and OUT. These spikes can potentially over-voltage the SW pin, or feed through to GND. To avoid this, COUT+ must be connected as closely as possible to the cathode of the Schottky diode, and COUT− must be connected as closely as possible to the LM3533 device's GND pin. The best placement for COUT is on the same layer as the LM3533 to avoid any vias that can add excessive series inductance.

10.1.1.2 Schottky Diode Placement

The Schottky diode must have a reverse breakdown voltage greater than the LM3533 maximum output voltage (see *[Overvoltage](#page-30-1) Protection (Inductive Boost)*). Additionally, the diode must have an average current rating high enough to handle the LM3533's maximum output current, and at the same time the diode's peak current rating must be high enough to handle the peak inductor current. Schottky diodes are required due to their lower forward voltage drop (0.3 V to 0.5 V) and their fast recovery time.

In the LM3533 boost circuit the Schottky diode is in the path of the inductor current discharge; thus, the Schottky diode sees a high-current step from 0 to I_{PEAK} each time the switch turns off and the diode turns on. Any inductance in series with the diode causes a voltage spike ($V_{SPIKE} = LP_x$ dl/dt) at SW and OUT. This can potentially over-voltage the SW pin, or feed through to V_{OUT} and through the output capacitor and into GND. Connecting the anode of the diode as closely as possible to the SW pin and the cathode of the diode as closely as possible to COUT+ reduces the inductance (LP_) and minimize these voltage spikes.

10.1.1.3 Inductor Placement

The node where the inductor connects to the LM3533's SW pin has 2 issues. First, a large switched voltage (0 to V_{OUT} + $V_{\text{F-SCHOTKY}}$) appears on this node every switching cycle. This switched voltage can be capacitively coupled into nearby nodes. Second, there is a relatively large current (input current) on the traces connecting the input supply to the inductor and connecting the inductor to the SW pin. Any resistance in this path can cause voltage drops that can negatively affect efficiency and reduce the input operating voltage range.

To reduce the capacitive coupling of the signal on SW into nearby traces, the SW pin-to-inductor connection must be minimized in area. This limits the PCB capacitance from SW to other traces. Additionally, highimpedance nodes that are more susceptible to electric field coupling need to be routed away from SW and not directly adjacent or beneath. This is especially true for traces such as SCL, SDA, HWEN, PWM, and possibly ALS. A GND plane placed directly below SW dramatically reduces the capacitance from SW into nearby traces.

Lastly, limit the trace resistance of the VBATT-to-inductor connection and from the inductor-to-SW connection, by use of short, wide traces.

Layout Guidelines (continued)

10.1.1.4 Boost Input Capacitor Selection and Placement

The input capacitor on the LM3533 filters the voltage ripple due to the switching action of the inductive boost and the capacitive charge pump doubler. A ceramic capacitor of at least 2.2 µF must be used.

For the LM3533 boost converter, the input capacitor filters the inductor current ripple and the internal MOSFET driver currents during turn on of the internal power switch. The driver current requirement can range from 50 mA at 2.7 V to over 200 mA at 5.5 V with fast durations of approximately 10 ns to 20 ns. This appears as high di/dt current pulses coming from the input capacitor each time the switch turns on. Close placement of the input capacitor to the IN pin and to the GND pin is critical because any series inductance between IN and CIN+ or CIN− and GND can create voltage spikes that could appear on the V_{IN} supply line and in the GND plane.

Close placement of the input bypass capacitor at the input side of the inductor is also critical. The source impedance (inductance and resistance) from the input supply, along with the input capacitor of the LM3533, form a series RLC circuit. If the output resistance from the source (R_s) is low enough the circuit is underdamped and has a resonant frequency (typically the case). Depending on the size of L_S the resonant frequency could occur below, close to, or above the LM3533 switching frequency. This can cause the supply current ripple to be:

- 1. Approximately equal to the inductor current ripple when the resonant frequency occurs well above the LM3533 switching frequency;
- 2. Greater than the inductor current ripple when the resonant frequency occurs near the switching frequency; or
- 3. Less than the inductor current ripple when the resonant frequency occurs well below the switching frequency. [Figure](#page-54-1) 54 shows the series RLC circuit formed from the output impedance of the supply and the input capacitor.

The circuit is redrawn for the AC case where the V_{IN} supply is replaced with a short to GND, and the LM3533 plus inductor is replaced with a current source (Δl_L). Equation 1 is the criteria for an underdamped response. Equation 2 is the resonant frequency. Equation 3 is the approximated supply current ripple as a function of LS, RS, and CIN.

As an example, consider a 3.6-V supply with 0.1 Ω of series resistance connected to C_{IN} through 50 nH of connecting traces. This results in an under-damped input-filter circuit with a resonant frequency of 712 kHz. Because both the 1-MHz and 500-kHz switching frequency options lie close to the resonant frequency of the input filter, the supply current ripple is probably larger than the inductor current ripple. In this case, using equation 3, the supply current ripple can be approximated as 1.68 times the inductor current ripple (using a 500 kHz switching frequency) and 0.86 times the inductor current ripple using a 1-MHz switching frequency. Increasing the series inductance (L_S) to 500 nH causes the resonant frequency to move to around 225 kHz, and the supply current ripple to be approximately 0.25 times the inductor current ripple (500-kHz switching frequency) and 0.053 times for a 1-MHz switching frequency.

[LM3533](http://www.ti.com.cn/product/cn/lm3533?qgpn=lm3533)

Layout Guidelines (continued)

Figure 54. Input RLC Network

10.1.2 Charge Pump

The charge pump basically has three areas of concern regarding component placement:

- 1. The flying capacitor (CP)
- 2. The output capacitor (CPOUT)
- 3. The input capacitor

10.1.2.1 Flying Capacitor (CP)

The charge pump flying capacitor must quickly charge up to the input voltage and then supply the current to the output every switching cycle. Because the charge pump switching frequency is 1 MHz, the capacitor must be a low-inductance and low-resistive ceramic. Additionally, there must be a low-inductive connection from CP to the LM3533 flying capacitor terminals C+ and C−. This is accomplished by placing CP as close as possible to the LM3533 and on the same layer to avoid vias.

10.1.2.2 Output Capacitor (CPOUT)

The charge pump output capacitor sees the switched charge from the flying capacitor every switching cycle (1 MHz). This fast switching action requires that a low inductive and low resistive capacitor (ceramic) be used and that CPOUT be connected to the LM3533 CPOUT pin with a low inductive connection. This is done by placing CPOUT as close as possible to the CPOUT and GND pins of the LM3533 and on the same layer as the LM3533 to avoid vias.

10.1.2.3 Charge Pump Input Capacitor Placement

The input capacitor for the LM3533 charge pump is the same one used for the LM3533 inductive boost converter (see *Boost Input Capacitor Selection and [Placement](#page-53-0)*).

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10.2 Layout Example

Figure 55. LM3533 Example Layout

11 器件和文档支持

11.1 器件支持

11.1.1 Third-Party Products Disclaimer

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11.2 相关文档

更多信息,请参见以下文档:

德州仪器 (TI) 应用手册 AN-1112《*DSBGA* 晶圆级芯片规模封装》(文献编号:[SNVA009](http://www.ti.com/cn/lit/pdf/SNVA009))。

11.3 社区资源

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms](http://www.ti.com/corp/docs/legal/termsofuse.shtml) of [Use.](http://www.ti.com/corp/docs/legal/termsofuse.shtml)

TI E2E™ Online [Community](http://e2e.ti.com) *TI's Engineer-to-Engineer (E2E) Community.* Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

Design [Support](http://support.ti.com/) *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

11.4 商标

E2E is a trademark of Texas Instruments. All other trademarks are the property of their respective owners.

11.5 静电放电警告

ESD 可能会损坏该集成电路。德州仪器 (TI) 建议通过适当的预防措施处理所有集成电路。如果不遵守正确的处理措施和安装程序 , 可 能会损坏集成电路。

<u>《《</u> SSD 的损坏小至导致微小的性能降级, 大至整个器件故障。精密的集成电路可能更容易受到损坏, 这是因为非常细微的参数更改都可 能会导致器件与其发布的规格不相符。

11.6 Glossary

[SLYZ022](http://www.ti.com/cn/lit/pdf/SLYZ022) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

12 机械、封装和可订购信息

以下页中包括机械、封装和可订购信息。 这些信息是针对指定器件可提供的最新数据。 这些数据会在无通知且不 对本文档进行修订的情况下发生改变。 要获得这份数据表的浏览器版本,请查阅左侧导航栏。

PACKAGING INFORMATION

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

⁽²⁾ RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures. "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the ≤ 1000 ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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TEXAS

TAPE AND REEL INFORMATION

ISTRUMENTS

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

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PACKAGE MATERIALS INFORMATION

*All dimensions are nominal

YFQ0020

B. This drawing is subject to change without notice.

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